

## Hilbert-Enskog-Chapman Expansion in the Turbulent Kinetic Theory of Gases. II

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This is a continuation of the article (I) with the same title. [Tian-quan Chen, preceding article *J. Stat. Phys.* **25**, 491 (1981).] We carry on with the Enskog-Chapman expansion here.

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**KEY WORDS:** BBGKY hierarchy; Enskog-Chapman expansion.

### 8.<sup>3</sup> 125 THIRD-ORDER CONSERVATION EQUATIONS

From 125 third-order summational invariants and the equation (3)<sup>3</sup> we can derive 125 third-order conservation equations. In order to write down these conservation equations we have to introduce the following notations:

$$S_{i_1 \dots i_l j_1 \dots j_m k_1 \dots k_n}^{(l, m, n)}$$

$$= \int h(z, \hat{z}, \check{z}, t) \prod_{r=1}^l (v_{i_r} - u_{i_r}) \prod_{s=1}^m (\hat{v}_{j_s} - \hat{u}_{j_s}) \prod_{t=1}^n (\check{v}_{k_t} - \check{u}_{k_t}) dv d\hat{v} d\check{v}$$

$$S_{i_1 \dots i_l j_1 \dots j_m k_1 \dots k_n}^{(l+2, m, n)} = S_{i_1 \dots i_l p p j_1 \dots j_m k_1 \dots k_n}^{(l+2, m, n)}$$

(on the right-hand side of the above equality, as well as throughout this section, the summation convention is implied), and

$$\frac{\Delta}{\Delta t} = \frac{\partial}{\partial t} + u_k \frac{\partial}{\partial x_k} + \hat{u}_k \frac{\partial}{\partial \hat{x}_k} + \check{u}_k \frac{\partial}{\partial \check{x}_k}$$

The 125 third-order conservation equations can be divided into ten

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<sup>3</sup> The ordinal numbers of the sections and the equations in this paper are consecutive with those in the preceding one.<sup>(1)</sup> When we refer to an equation in Ref. 1, we shall just refer to the number of the equation, without citing Ref. 1.

classes, of which the typical equations are as follows:

$$\begin{aligned} \frac{\Delta S^{(0,0,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(0,0,0)} + \frac{\partial S_k^{(1,0,0)}}{\partial x_k} \\ + \frac{\partial S_k^{(0,1,0)}}{\partial \hat{x}_k} + \frac{\partial S_k^{(0,0,1)}}{\partial \check{x}_k} = 0 \end{aligned} \quad (62)$$

$$\begin{aligned} \frac{\Delta S_i^{(1,0,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_i^{(1,0,0)} + \frac{Du_i}{Dt} S^{(0,0,0)} \\ + S_k^{(1,0,0)} \frac{\partial u_i}{\partial x_k} + \frac{\partial S_{i,k}^{(1,1,0)}}{\partial \hat{x}_k} + \frac{\partial S_{i,k}^{(1,0,1)}}{\partial \check{x}_k} + \frac{\partial S_{ki}^{(2,0,0)}}{\partial x_k} \\ = 0 \quad (1 \leq i \leq 3) \end{aligned} \quad (63)$$

$$\begin{aligned} \frac{\Delta S_{ij}^{(1,1,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_{ij}^{(1,1,0)} + \frac{Du_i}{Dt} S_{j,l}^{(0,1,1)} \\ + \frac{\hat{D}\hat{u}_j}{\hat{D}t} S_i^{(1,0,0)} + \frac{\partial u_i}{\partial x_k} S_{kj}^{(1,1,0)} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S_{i,k}^{(1,1,0)} + \frac{\partial S_{ikj}^{(2,1,0)}}{\partial x_k} \\ + \frac{\partial S_{ijk}^{(1,2,0)}}{\partial \hat{x}_k} + \frac{\partial S_{ij,k}^{(1,1,1)}}{\partial \check{x}_k} = 0 \quad (1 \leq i, j \leq 3) \end{aligned} \quad (64)$$

$$\begin{aligned} \frac{\Delta S_{ij,l}^{(1,1,1)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_{ij,l}^{(1,1,1)} + \frac{Du_i}{Dt} S_{j,l}^{(0,1,1)} \\ + \frac{\hat{D}\hat{u}_j}{\hat{D}t} S_{i,l}^{(1,0,1)} + \frac{\check{D}\check{u}_l}{\check{D}t} S_{ij}^{(1,1,0)} + \frac{\partial u_i}{\partial x_k} S_{kj,l}^{(1,1,1)} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S_{i,k,l}^{(1,1,1)} \\ + \frac{\partial \check{u}_l}{\partial \check{x}_k} S_{ij,k}^{(1,1,1)} + \frac{\partial S_{kij,l}^{(2,1,1)}}{\partial x_k} + \frac{\partial S_{i,kj,l}^{(1,2,1)}}{\partial \hat{x}_k} + \frac{\partial S_{ij,kl}^{(1,1,2)}}{\partial \check{x}_k} = 0 \\ (1 \leq i, j, l \leq 3) \end{aligned} \quad (65)$$

$$\begin{aligned} \frac{\Delta S^{(2,0,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,0,0)} + 2S_k^{(1,0,0)} \frac{Du_k}{Dt} \\ + 2 \frac{\partial u_k}{\partial x_s} S_{ks}^{(2,0,0)} + \frac{\partial S_k^{(3,0,0)}}{\partial x_k} + \frac{\partial S_k^{(2,1,0)}}{\partial \hat{x}_k} + \frac{\partial S_k^{(2,0,1)}}{\partial \check{x}_k} = 0 \end{aligned} \quad (66)$$

$$\begin{aligned}
 & \frac{\Delta S^{(2,1,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,1,0)} + 2S^{(1,1,0)} \frac{Du_k}{Dt} \\
 & + S^{(2,0,0)} \frac{\hat{D}\hat{u}_j}{\hat{D}t} + 2 \frac{\partial u_k}{\partial x_s} S^{(2,1,0)}_{ksj} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S^{(2,1,0)}_k + \frac{\partial S^{(3,1,0)}_{kj}}{\partial x_k} \\
 & + \frac{\partial S^{(2,2,0)}_{kj}}{\partial \hat{x}_k} + \frac{\partial S^{(2,1,1)}_{j,k}}{\partial \check{x}_k} = 0 \quad (1 \leq j \leq 3) \quad (67)
 \end{aligned}$$

$$\begin{aligned}
 & \frac{\Delta S^{(2,1,1)}_{j,l}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,1,1)}_{j,l} + 2 \frac{Du_k}{Dt} S^{(1,1,1)}_{k,j,l} \\
 & + \frac{\hat{D}\hat{u}_j}{\hat{D}t} S^{(2,0,1)}_{l} + \frac{\check{D}\check{u}_l}{\check{D}t} S^{(2,1,0)}_j + 2 \frac{\partial u_k}{\partial x_s} S^{(2,1,1)}_{ks,j,l} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S^{(2,1,1)}_{k,l} \\
 & + \frac{\partial \check{u}_l}{\partial \check{x}_k} S^{(2,1,1)}_{j,k} + \frac{\partial S^{(3,1,1)}_{k,j,l}}{\partial x_k} + \frac{\partial S^{(2,2,1)}_{kj,l}}{\partial \hat{x}_k} + \frac{\partial S^{(2,1,2)}_{j,kl}}{\partial \check{x}_k} = 0 \\
 & (1 \leq j, l \leq 3) \quad (68)
 \end{aligned}$$

$$\begin{aligned}
 & \frac{\Delta S^{(2,2,1)}_l}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,2,1)}_l + 2 \frac{Du_k}{Dt} S^{(1,2,1)}_{k,l} \\
 & + 2 \frac{\hat{D}\hat{u}_k}{\hat{D}t} S^{(2,1,1)}_{k,l} + \frac{\check{D}\check{u}_l}{\check{D}t} S^{(2,2,0)} + 2 \frac{\partial u_k}{\partial x_s} S^{(2,2,1)}_{ks,l} + 2 \frac{\partial \hat{u}_k}{\partial \hat{x}_s} S^{(2,2,1)}_{ks,l} \\
 & + \frac{\partial \check{u}_l}{\partial \check{x}_k} S^{(2,2,1)}_k + \frac{\partial S^{(3,2,1)}_{k,l}}{\partial x_k} + \frac{\partial S^{(2,3,1)}_{k,l}}{\partial \hat{x}_k} + \frac{\partial S^{(2,2,2)}_{kl}}{\partial \check{x}_k} = 0 \\
 & (1 \leq l \leq 3) \quad (69)
 \end{aligned}$$

$$\begin{aligned}
 & \frac{\Delta S^{(2,2,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,2,0)} + 2 \frac{Du_k}{Dt} S^{(1,2,0)}_k \\
 & + 2 \frac{\hat{D}\hat{u}_k}{\hat{D}t} S^{(2,1,0)}_k + 2 \frac{\partial u_k}{\partial x_s} S^{(2,2,0)}_{ks} + 2 \frac{\partial \hat{u}_k}{\partial \hat{x}_s} S^{(2,2,0)}_{ks} + \frac{\partial S^{(3,2,0)}_k}{\partial x_k} \\
 & + \frac{\partial S^{(2,3,0)}_k}{\partial \hat{x}_k} + \frac{\partial S^{(2,2,1)}_k}{\partial \check{x}_k} = 0 \quad (70)
 \end{aligned}$$

$$\begin{aligned}
& \frac{\Delta S^{(2,2,2)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,2,2)} + 2 \frac{Du_k}{Dt} S^{(1,2,2)}_k \\
& + 2 \frac{\hat{D}\hat{u}_k}{\hat{D}t} S^{(2,1,2)}_k + 2 \frac{\check{D}\check{u}_k}{\check{D}t} S^{(2,2,1)}_k + 2 \frac{\partial u_k}{\partial x_s} S^{(2,2,2)}_{ks} + 2 \frac{\partial \hat{u}_k}{\partial \hat{x}_s} S^{(2,2,2)}_{ks} \\
& + 2 \frac{\partial \check{u}_k}{\partial \check{x}_s} S^{(2,2,2)}_{ks} + \frac{\partial S^{(3,2,2)}_k}{\partial x_k} + \frac{\partial S^{(2,3,2)}_k}{\partial \hat{x}_k} + \frac{\partial S^{(2,2,3)}_k}{\partial \check{x}_k} = 0 \quad (71)
\end{aligned}$$

## 9. THE SOLUTION OF EQUATION (30)

In order to solve equation (30) we have to calculate the right-hand side of the equation. On account of (34), (45), (46), and (47), we have

$$\begin{aligned}
& \mathcal{G}[g^{(1)}g^{(1)}]_{\hat{z}\check{z}} \\
& = \int \left[ g^{(1)}(z', \hat{z})g^{(1)}(\check{z}', \check{z}) + g^{(1)}(\check{z}', \hat{z})g^{(1)}(z', \check{z}) \right. \\
& \quad \left. - g^{(1)}(z, \hat{z})g^{(1)}(\check{z}, \check{z}) - g^{(1)}(\check{z}, \hat{z})g^{(1)}(z, \check{z}) \right] B(\theta) d\epsilon d\theta d\check{\nu} \\
& = f^{(0)}\hat{f}^{(0)}\check{f}^{(0)} \left[ \sum_{0 \leq i, j, s, t \leq 4} a_{ij}(x, \hat{x}) a_{st}(x, \check{x}) \hat{\psi}_j \check{\psi}_t \right. \\
& \quad \left. \times \int \check{f}^{(0)}(\psi'_i \check{\psi}'_s + \check{\psi}'_i \psi'_s - \psi_i \check{\psi}_s - \check{\psi}_i \psi_s) B(\theta) d\epsilon d\theta d\check{\nu} \right] \\
& = f^{(0)}\hat{f}^{(0)}\check{f}^{(0)} \sum_{0 \leq j, t \leq 4} \hat{\psi}_j \check{\psi}_t \left\{ 6B_1 n \sum_{1 \leq i, s \leq 3} a_{ij}(x, \hat{x}) a_{st}(x, \check{x}) \left( w_i w_s - \frac{1}{3} \delta_{is} |w|^2 \right) \right. \\
& \quad + 4B_1 n \sum_{1 \leq i \leq 3} \left[ a_{ij}(x, \hat{x}) a_{4t}(x, \check{x}) + a_{4j}(x, \hat{x}) \right. \\
& \quad \left. \left. \times a_{it}(x, \check{x}) \right] \left( |w|^2 w_i - \frac{5KT}{m} w_i \right) \right. \\
& \quad + 4B_1 n a_{4j}(x, \hat{x}) a_{4t}(x, \check{x}) \\
& \quad \left. \times \left[ |w|^4 - 10|w|^2 \frac{KT}{m} + 15 \left( \frac{KT}{m} \right)^2 \right] \right\} \quad (72)
\end{aligned}$$

The expressions for  $\mathcal{G}[g^{(1)}g^{(1)}]_{\hat{z}\hat{z}}$  and  $\mathcal{G}[g^{(1)}g^{(1)}]_{\check{z}\check{z}}$  can be obtained from the above expression by exchanging  $z \leftrightarrow \check{z}$  and  $z \leftrightarrow \hat{z}$ , respectively. Multiplying the sum of these three expressions by  $(-1)$ , we get the expression for the

right-hand side of equation (30). In virtue of Wang-Chang and Uhlenbeck's results on the eigenfunctions and eigenvalues of the linear Boltzmann operator,<sup>(2)</sup> we get the solution of equation (30) as follows:

$$\begin{aligned}
 h^{(2)} = & f^{(0)}\hat{f}^{(0)}\check{f}^{(0)} \sum_{0 < j, t < 4} \hat{\psi}_j \check{\psi}_t \left\{ \sum_{1 < i, s < 3} a_{ij}(x, \hat{x}) a_{st}(x, \check{x}) \left( w_i w_s - \frac{1}{3} \delta_{is} |w|^2 \right) \right. \\
 & + \sum_{1 < i < 3} [ a_{ij}(x, \hat{x}) a_{it}(x, \check{x}) + a_{aj}(x, \hat{x}) a_{it}(x, \check{x}) ] \\
 & \times \left( |w|^2 w_i - \frac{5KT}{m} w_i \right) + a_{aj}(x, \hat{x}) a_{at}(x, \check{x}) \\
 & \left. \times \left[ |w|^4 - 10|w|^2 \frac{KT}{m} + 15 \left( \frac{KT}{m} \right)^2 \right] \right\} \\
 & + \text{(the sum of two expressions obtained from the above expression} \\
 & \quad \text{by exchanging } z \leftrightarrow \text{ and } z \leftrightarrow \hat{z}, \text{ respectively)} \\
 & + f^{(0)}\hat{f}^{(0)}\check{f}^{(0)} \sum_{0 \leq i, j, k < 4} b_{ij} \psi_i \hat{\psi}_j \check{\psi}_k
 \end{aligned}$$

On account of the additional integral conditions imposed on  $h^{(2)}$  we have the following relations between 125  $S$ 's and 125  $b_{ijk}$ 's. 125  $b_{ijk}$ 's can be divided into ten classes each of which is expressed in terms of  $S$ 's as follows (the indices  $i, j, k$  in the following formulas denote the numbers 1, 2, and 3. The numbers 0 and 4 will be explicitly indicated):

$$b_{ijk} = \frac{m^3}{n\hat{n}\check{n}K^3\hat{T}\check{T}} S_{ij,k}^{(1,1,1)} \tag{73}$$

$$b_{0jk} = \frac{m^3}{2n\hat{n}\check{n}K^3\hat{T}\check{T}} \left( \frac{5KT}{m} S_{j,k}^{(0,1,1)} - S_{j,k}^{(2,1,1)} \right) \tag{74}$$

$$b_{4jk} = \frac{m^4}{6n\hat{n}\check{n}K^4T^2\hat{T}\check{T}} \left( S_{j,k}^{(2,1,1)} - \frac{3KT}{m} S_{j,k}^{(0,1,1)} \right) \tag{75}$$

$$\begin{aligned}
 b_{44k} = & \frac{m^5}{36n\hat{n}\check{n}K^5T^2\hat{T}^2\check{T}} \left( S_k^{(2,2,1)} - \frac{3K\hat{T}}{m} S_k^{(2,0,1)} - \frac{3KT}{m} S_k^{(0,2,1)} \right. \\
 & \left. + \frac{9K^2T\hat{T}}{m^2} S_k^{(0,0,1)} \right) \tag{76}
 \end{aligned}$$

$$\begin{aligned}
 b_{04k} = & \frac{m^4}{12n\hat{n}\check{n}K^4T\hat{T}^2\check{T}} \left( -S_k^{(2,2,1)} + \frac{3K\hat{T}}{m} S_k^{(2,0,1)} + \frac{5KT}{m} S_k^{(0,2,1)} \right. \\
 & \left. - \frac{15K^2T\hat{T}}{m^2} S_k^{(0,0,1)} \right) \tag{77}
 \end{aligned}$$

$$b_{00k} = \frac{m^3}{4n\hat{n}\check{n}K^3T\hat{T}\check{T}} \left( S^{(2,2,1)}_k - \frac{5K\hat{T}}{m} S^{(2,0,1)}_k - \frac{5KT}{m} S^{(0,2,1)}_k \right. \\ \left. + \frac{25K^2T\hat{T}}{m^2} S^{(0,0,1)}_k \right) \quad (78)$$

$$b_{444} = \frac{m^6}{216n\hat{n}\check{n}K^6T^2\hat{T}^2\check{T}^2} \left[ S^{(2,2,2)} - \frac{3K}{m} (\check{T}S^{(2,2,0)} + \hat{T}S^{(2,0,2)} + TS^{(0,2,2)}) \right. \\ \left. + \frac{9K^2}{m^2} (T\hat{T}S^{(0,0,2)} + T\check{T}S^{(0,2,0)} + \hat{T}\check{T}S^{(2,0,0)}) \right. \\ \left. - 27 \frac{K^3T\hat{T}\check{T}}{m^3} S^{(0,0,0)} \right] \quad (79)$$

$$b_{404} = \frac{m^5}{72n\hat{n}\check{n}K^5T^2\hat{T}\check{T}^2} \left[ -S^{(2,2,2)} + 3 \left( \frac{K\check{T}}{m} S^{(2,2,0)} + \frac{KT}{m} S^{(0,2,2)} \right) \right. \\ \left. + 5 \frac{K\hat{T}}{m} S^{(2,0,2)} - 9 \frac{K^2T\check{T}}{m^2} S^{(0,2,0)} \right. \\ \left. - 15 \left( \frac{K^2T\hat{T}}{m^2} S^{(0,0,2)} + \frac{K^2\hat{T}\check{T}}{m^2} S^{(2,0,0)} \right) \right. \\ \left. + 45 \frac{K^3T\hat{T}\check{T}}{m^3} S^{(0,0,0)} \right] \quad (80)$$

$$b_{004} = \frac{m^4}{24n\hat{n}\check{n}K^4T\hat{T}\check{T}^2} \left[ S^{(2,2,2)} - 5 \left( \frac{K\hat{T}}{m} S^{(2,0,2)} + \frac{KT}{m} S^{(0,2,2)} \right) \right. \\ \left. - 3 \frac{K\check{T}}{m} S^{(2,2,0)} + 15 \left( \frac{K^2\hat{T}\check{T}}{m^2} S^{(2,0,0)} + \frac{K^2T\check{T}}{m^2} S^{(0,2,0)} \right) \right. \\ \left. + 25 \frac{K^2T\hat{T}}{m^2} S^{(0,0,2)} - 75 \frac{K^3T\hat{T}\check{T}}{m^3} S^{(0,0,0)} \right] \quad (81)$$

$$b_{000} = \frac{m^3}{8n\hat{n}\check{n}K^3T\hat{T}\check{T}} \left[ -S^{(2,2,2)} + 5 \left( \frac{KT}{m} S^{(0,2,2)} + \frac{K\hat{T}}{m} S^{(2,0,2)} + \frac{K\check{T}}{m} S^{(2,2,0)} \right) \right. \\ \left. - 25 \left( \frac{K^2\hat{T}\check{T}}{m^2} S^{(2,0,0)} + \frac{K^2T\check{T}}{m^2} S^{(0,2,0)} + \frac{K^2T\hat{T}}{m^2} S^{(0,0,2)} \right) \right. \\ \left. + 125 \frac{K^3T\hat{T}\check{T}}{m^3} S^{(0,0,0)} \right] \quad (82)$$

10. THE CALCULATION OF  $J[h^{(2)}(z', \hat{z}, \tilde{z}') - h^{(2)}(z, \hat{z}, \tilde{z})]_{\tilde{x}=x}$

It is easily seen from (72) that

$$\begin{aligned}
 & J[h^{(2)}(z', \hat{z}, \tilde{z}') - h^{(2)}(z, \hat{z}, \tilde{z})]_{\tilde{x}=x} \\
 &= \hat{f}^{(0)} \sum_{0 \leq j \leq 4} \hat{\psi}_j \left\{ \sum_{\substack{0 \leq i \leq 4 \\ 1 \leq i, s \leq 3}} a_{ij}(x, \hat{x}) a_{st}(x, x) \right. \\
 &\quad \times J \left[ f^{(0)} \tilde{f}^{(0)} \left\{ d_c \tilde{\psi}_i \left( w_i w_s - \frac{1}{3} \delta_{is} |w|^2 \right) \right\} \right] \\
 &\quad + \sum_{\substack{1 \leq i \leq 3 \\ 0 \leq t \leq 4}} [a_{ij}(x, \hat{x}) a_{4t}(x, x) + a_{4j}(x, \hat{x}) a_{it}(x, x)] \\
 &\quad \times J \left[ f^{(0)} \tilde{f}^{(0)} \left\{ d_c \tilde{\psi}_i \left( |w|^2 w_i - \frac{5KT}{m} w_i \right) \right\} \right] \\
 &\quad + \sum_{0 \leq t \leq 4} a_{4j}(x, \hat{x}) a_{4t}(x, x) \\
 &\quad \times J \left[ f^{(0)} \tilde{f}^{(0)} \left\{ d_c \tilde{\psi}_i \left( |w|^4 - 10|w|^2 \frac{KT}{m} + 15 \left( \frac{KT}{m} \right)^2 \right) \right\} \right] \Bigg\} \\
 &+ \frac{1}{2} \hat{f}^{(0)} \sum_{0 \leq j, t \leq 4} J[f^{(0)} \tilde{f}^{(0)}(d_c \psi_j \tilde{\psi}_t)] \\
 &\times \left\{ \sum_{1 \leq i, s \leq 3} a_{ij}(\hat{x}, x) a_{st}(\hat{x}, x) \left( \hat{w}_i \hat{w}_s - \frac{1}{3} \delta_{is} |\hat{w}|^2 \right) \right. \\
 &\quad + \sum_{1 \leq i \leq 3} [a_{ij}(\hat{x}, x) a_{4t}(\hat{x}, x) + a_{4j}(\hat{x}, x) a_{it}(\hat{x}, x)] \left( |\hat{w}|^2 \hat{w}_i - \frac{5KT}{m} \hat{w}_i \right) \\
 &\quad + a_{4j}(\hat{x}, x) a_{4t}(\hat{x}, x) \left[ |\hat{w}|^4 - 10|\hat{w}|^2 \frac{KT}{m} + 15 \left( \frac{KT}{m} \right)^2 \right] \\
 &\quad \left. + \sum_{0 \leq i \leq 4} b_{ji}(x, \hat{x}, x) \hat{\psi}_i \right\} \tag{83}
 \end{aligned}$$

Where  $d_c$  denotes the collision difference operator:

$$d_c \tilde{f} g = \tilde{f}' g' + f' \tilde{g}' - \tilde{f} g - f g$$

In order to calculate the right-hand side of the equation (83), besides the formulas (45), (46), (47) and Wang-Chang and Uhlenbeck's results on the eigenfunctions and eigenvalues of the linear Boltzmann integral operator we need some additional formulas.

Let  $A$ ,  $B$ , and  $C$  be three (three-dimensional) vectors with coordinates  $a_i$ ,  $b_i$ , and  $c_i$  ( $i = 1, 2, 3$ ), respectively. The triadic product  $ABC$  of the vectors  $A$ ,  $B$ , and  $C$  is defined as a tensor of rank 3 with components

$$(ABC)_{ijk} = a_i b_j c_k$$

Moreover,  $\delta A$ ,  $A\delta$  and  $\delta^{1/2}A\delta^{1/2}$  denote three tensors of rank 3 with the following components, respectively:

$$(\delta A)_{ijk} = \delta_{ij} a_k, \quad (A\delta)_{ijk} = a_i \delta_{jk}, \quad (\delta^{1/2}A\delta^{1/2})_{ijk} = \delta_{ik} a_j$$

Now we begin to derive the formulas we need. A simple calculation shows that

$$\begin{aligned} & \tilde{w}' w' w' + w' \tilde{w}' \tilde{w}' - \tilde{w} w w - w \tilde{w} \tilde{w} \\ &= [\tilde{w} - \alpha(\alpha \cdot U)][w + \alpha(\alpha \cdot U)][w + \alpha(\alpha \cdot U)] \\ & \quad + [w + \alpha(\alpha \cdot U)][\tilde{w} - \alpha(\alpha \cdot U)][\tilde{w} - \alpha(\alpha \cdot U)] - \tilde{w} w w - w \tilde{w} \tilde{w} \\ &= (\tilde{w} w - w \tilde{w})\alpha(\alpha \cdot U) + (\tilde{w} \alpha w - w \alpha \tilde{w})(\alpha \cdot U) + (\tilde{w} + w)\alpha\alpha(\alpha \cdot U)^2 \\ & \quad + \alpha(\tilde{w} \tilde{w} - w w)(\alpha \cdot U) - \alpha(w + \tilde{w})\alpha(\alpha \cdot U)^2 - \alpha\alpha(w + \tilde{w})(\alpha \cdot U)^2 \end{aligned}$$

The following formula is similar to formula (44) and can be proved in a similar way:

$$\int \alpha A \alpha d\epsilon = \pi \sin^2 \theta \delta^{1/2} A \delta^{1/2} + 2\pi \left(1 - \frac{3}{2} \sin^2 \theta\right) \frac{U A U}{|U|^2} \quad (84)$$

From formulas (43), (44), (84) and the lemma in Section 6 we can derive the following formula:

$$\begin{aligned} \int d_c(\tilde{w} w w) d\epsilon &= (\tilde{w} w - w \tilde{w}) U \frac{2\pi \cos \theta}{|U|} (\alpha \cdot U) + (\tilde{w} U w - w U \tilde{w}) 2\pi \cos^2 \theta \\ & \quad + (\alpha \cdot U)^2 (\tilde{w} + w) \left[ \pi \sin^2 \theta \delta + 2\pi \left(1 - \frac{3}{2} \sin^2 \theta\right) \frac{U U}{|U|^2} \right] \\ & \quad + U(\tilde{w} \tilde{w} - w w) 2\pi \cos^2 \theta \\ & \quad - (\alpha \cdot U)^2 \left[ \pi \sin^2 \theta \delta^{1/2} (w + \tilde{w}) \delta^{1/2} \right. \\ & \quad \quad \left. + 2\pi \left(1 - \frac{3}{2} \sin^2 \theta\right) \frac{U(w + \tilde{w})U}{|U|^2} \right] \\ & \quad - (\alpha \cdot U)^2 \left[ \pi \sin^2 \theta \delta + 2\pi \left(1 - \frac{3}{2} \sin^2 \theta\right) \frac{U U}{|U|^2} \right] (w + \tilde{w}) = \end{aligned}$$



$$\begin{aligned}
&= \pi \cos^2 \theta \sin^2 \theta \left[ (\tilde{w} + w) \delta |U|^2 - \delta^{1/2} (\tilde{w} + w) \delta^{1/2} |U|^2 \right. \\
&\quad - \delta (\tilde{w} + w) |U|^2 - 3(\tilde{w} + w) UU \\
&\quad \left. + 3U(\tilde{w} + w)U + 3UU(\tilde{w} + w) \right] \\
&= \pi \cos^2 \theta \sin^2 \theta \left\{ 3(\tilde{w}w\tilde{w} + w\tilde{w}w + \tilde{w}\tilde{w}\tilde{w} + \tilde{w}\tilde{w}w + w\tilde{w}\tilde{w} + w\tilde{w}w) \right. \\
&\quad - 9(w\tilde{w}\tilde{w} + \tilde{w}\tilde{w}w) + (|w|^2 + |\tilde{w}|^2 - 2w \cdot \tilde{w}) \\
&\quad \left. \times [(\tilde{w} + w)\delta - \delta^{1/2}(\tilde{w} + w)\delta^{1/2} - \delta(\tilde{w} + w)] \right\}
\end{aligned}$$

Hence,

$$\begin{aligned}
&\int f^{(0)} \tilde{f}^{(0)} d_c(\tilde{w}w) B(\theta) d\theta d\epsilon d\tilde{v} \\
&= B_1 n f^{(0)} \left[ \frac{3KT}{m} \delta^{1/2} w \delta^{1/2} + \frac{3KT}{m} \delta w + 3w\tilde{w}w - \frac{9KT}{m} w\delta \right. \\
&\quad + w\delta \left( |w|^2 + \frac{3KT}{m} \right) - \frac{2KT}{m} w\delta - \left( |w|^2 + \frac{3KT}{m} \right) \delta^{1/2} w \delta^{1/2} \\
&\quad \left. + \frac{2KT}{m} \delta^{1/2} w \delta^{1/2} - \left( |w|^2 + \frac{3KT}{m} \right) \delta w + \frac{2KT}{m} \delta w \right] \\
&= B_1 n f^{(0)} \left[ |w|^2 (w\delta - \delta w - \delta^{1/2} w \delta^{1/2}) \right. \\
&\quad \left. + \frac{2KT}{m} (\delta^{1/2} w \delta^{1/2} + \delta w - 4w\delta) + 3w\tilde{w}w \right] \quad (85)
\end{aligned}$$

Combining (85) with (46), we have

$$\begin{aligned}
&\int f^{(0)} \tilde{f}^{(0)} d_c \left[ \tilde{w} \left( w\tilde{w} - \frac{1}{3} |w|^2 \delta \right) \right] B(\theta) d\theta d\epsilon d\tilde{v} \\
&= B_1 n f^{(0)} \left\{ 3 \left[ w\tilde{w}w - \frac{1}{5} (w\delta + \delta w + \delta^{1/2} w \delta^{1/2}) |w|^2 \right] \right. \\
&\quad + \frac{4}{15} \left( |w|^2 - \frac{5KT}{m} \right) w\delta - \frac{2}{5} \left( |w|^2 - \frac{5KT}{m} \right) \\
&\quad \left. \times (\delta w + \delta^{1/2} w \delta^{1/2}) \right\}
\end{aligned}$$

$$\begin{aligned}
& |\tilde{w}'|^2 w' w' + |w'|^2 \tilde{w}' \tilde{w}' - |\tilde{w}|^2 w w - |w|^2 \tilde{w} \tilde{w} \\
&= [|\tilde{w}|^2 + (\alpha \cdot U)^2 - 2(\alpha \cdot U)(\alpha \cdot \tilde{w})][w + \alpha(\alpha \cdot U)][w + \alpha(\alpha \cdot U)] \\
&\quad + [ |w|^2 + (\alpha \cdot U)^2 + 2(\alpha \cdot U)(\alpha \cdot w) ] [\tilde{w} - \alpha(\alpha \cdot U)][\tilde{w} - \alpha(\alpha \cdot U)] \\
&\quad - |\tilde{w}|^2 w w - |w|^2 \tilde{w} \tilde{w} = |\tilde{w}|^2 (\alpha \cdot U)(\alpha w + w \alpha) - |w|^2 (\alpha \cdot U)(\alpha \tilde{w} + \tilde{w} \alpha) \\
&\quad + (|w|^2 + |\tilde{w}|^2)(\alpha \cdot U)^2 \alpha \alpha + (w w + \tilde{w} \tilde{w})(\alpha \cdot U)^2 - (\alpha U + U \alpha)(\alpha \cdot U)^3 \\
&\quad - 2(\alpha \cdot U)[(\alpha \cdot \tilde{w}) w w - (\alpha \cdot w) \tilde{w} \tilde{w}] \\
&\quad - 2(\alpha \cdot U)^2 [(\alpha \cdot \tilde{w})(w \alpha + \alpha w) + (\alpha \cdot w)(\tilde{w} \alpha + \alpha \tilde{w})] \tag{86}
\end{aligned}$$

The following formula can be derived in a way similar to that of the formula (44):

$$\int (\alpha \cdot A) B \alpha d\epsilon = \pi \sin^2 \theta B A + 2\pi \left(1 - \frac{3}{2} \sin^2 \theta\right) \frac{(A \cdot U) B U}{|U|^2} \tag{87}$$

From formulas (43), (44), (87) and the lemma in Section 6, we can derive the following formula:

$$\begin{aligned}
& \int d_c (|w|^2 \tilde{w} \tilde{w}) d\epsilon \\
&= \pi \cos^2 \theta \sin^2 \theta [ (|\tilde{w}|^2 + |w|^2)(|U|^2 \delta - 3 U U) + 4 |U|^2 U U \\
&\quad - 4 |U|^2 (w \tilde{w} + \tilde{w} w) + 6 (U \cdot \tilde{w})(w U + U w) \\
&\quad + 6 (U \cdot w)(\tilde{w} U + U \tilde{w}) ] \\
&= \pi \cos^2 \theta \sin^2 \theta \{ |w|^2 w w + |\tilde{w}|^2 \tilde{w} \tilde{w} + (|w|^2 + |\tilde{w}|^2)(\tilde{w} w + w \tilde{w}) \\
&\quad + 4 (w \cdot \tilde{w})(w w + \tilde{w} \tilde{w} + \tilde{w} w + w \tilde{w}) + (|\tilde{w}|^2 + |w|^2) \\
&\quad [ |\tilde{w}|^2 + |w|^2 - 2(\tilde{w} \cdot w) ] \delta - 11 (|w|^2 \tilde{w} \tilde{w} + |\tilde{w}|^2 w w) \}
\end{aligned}$$

Hence,

$$\begin{aligned}
\int f^{(0)} \tilde{f}^{(0)} d_c (|w|^2 \tilde{w} \tilde{w}) B(\theta) d\theta d\epsilon d\tilde{v} &= B_1 n f^{(0)} \left[ |w|^4 \delta + |w|^2 w w - 25 \frac{KT}{m} w w \right. \\
&\quad \left. - 5 \frac{KT}{m} |w|^2 \delta + 20 \left( \frac{KT}{m} \right)^2 \delta \right] \tag{88}
\end{aligned}$$

By virtue of the equalities (88), (47) and Uhlenbeck and Wang-Chang's result about the eigenfunctions and eigenvalues of the linear Boltzmann integral operator, we get

$$\int f^{(0)} \tilde{f}^{(0)} d_c \left[ \left( |w|^2 - \frac{3KT}{m} \right) \left( \tilde{w}\tilde{w} - \frac{1}{3} |\tilde{w}|^2 \delta \right) \right] B(\theta) d\theta d\epsilon d\tilde{w}$$

$$= -\frac{1}{3} B_1 n f^{(0)} \left( |w|^4 \delta - 3|w|^2 w w - \frac{7KT}{m} |w|^2 \delta + 21 \frac{KT}{m} w w \right) \quad (89)$$

$$\begin{aligned} & |w'|^2 w' \tilde{w}' + |\tilde{w}'|^2 \tilde{w}' w' - |w|^2 w \tilde{w} - |\tilde{w}|^2 \tilde{w} w \\ &= |w + \alpha(\alpha \cdot U)|^2 [w + \alpha(\alpha \cdot U)] [\tilde{w} - \alpha(\alpha \cdot U)] \\ &\quad + |\tilde{w} - \alpha(\alpha \cdot U)|^2 [\tilde{w} - \alpha(\alpha \cdot U)] [w + \alpha(\alpha \cdot U)] \\ &\quad - |w|^2 w \tilde{w} - |\tilde{w}|^2 \tilde{w} w \\ &= |w|^2 (\alpha \cdot U) (\alpha \tilde{w} - w \alpha) + |\tilde{w}|^2 (\alpha \cdot U) (\tilde{w} \alpha - \alpha w) \\ &\quad - (|w|^2 + |\tilde{w}|^2) (\alpha \cdot U) \alpha \alpha + 2(\alpha \cdot U) [(\alpha \cdot w) w \tilde{w} - (\alpha \cdot \tilde{w}) \tilde{w} w] \\ &\quad + 2(\alpha \cdot U)^2 [(\alpha \cdot w) (\alpha \tilde{w} - w \alpha) - (\alpha \cdot \tilde{w}) (\tilde{w} \alpha - \alpha w)] \\ &\quad + (\alpha \cdot U)^2 (w \tilde{w} + \tilde{w} w) + (\alpha \cdot U)^3 (\alpha \tilde{w} + \tilde{w} \alpha - \alpha w - w \alpha) \end{aligned}$$

From formulas (43), (44), (87) and the lemma in Section 6 we can derive the following formula:

$$\begin{aligned} & \int d_c (|w|^2 w \tilde{w}) d\epsilon \\ &= -(|w|^2 + |\tilde{w}|^2) \pi \cos^2 \theta \sin^2 \theta (|U|^2 \delta - 3UU) \\ &\quad - 2\pi \cos^2 \theta \sin^2 \theta |U|^2 (U\tilde{w} + \tilde{w}U - Uw - wU) \\ &\quad + 2\pi \cos^2 \theta \sin^2 \theta [ |U|^2 w \tilde{w} - 3(U \cdot w) U \tilde{w} - |U|^2 w w \\ &\quad \quad + 3(U \cdot w) w U + |U|^2 \tilde{w} w - 3(U \cdot \tilde{w}) U w \\ &\quad \quad - |U|^2 \tilde{w} \tilde{w} + 3(U \cdot \tilde{w}) \tilde{w} U ] \\ &= \pi \cos^2 \theta \sin^2 \theta \left\{ 3(|w|^2 + |\tilde{w}|^2) (w w + \tilde{w} \tilde{w}) + 3|w|^2 \tilde{w} w \right. \\ &\quad \quad + 3|\tilde{w}|^2 w \tilde{w} - 9|w|^2 w \tilde{w} - 9|\tilde{w}|^2 \tilde{w} w \\ &\quad \quad \left. - (|w|^2 + |\tilde{w}|^2) [ |w|^2 + |\tilde{w}|^2 - 2(w \cdot \tilde{w}) ] \delta \right\} \end{aligned}$$

Hence,

$$\begin{aligned} & \int f^{(0)} \tilde{f}^{(0)} d_c (|w|^2 w \tilde{w}) B(\theta) d\theta d\epsilon d\tilde{v} \\ &= B_1 n f^{(0)} \left( -|w|^4 \delta + 3 w w |w|^2 - \frac{3KT}{m} |w|^2 \delta + \frac{9KT}{m} w w \right) \end{aligned} \quad (90)$$

Combining formula (90) with formula (45), we have

$$\begin{aligned} & \int f^{(0)} \tilde{f}^{(0)} d_c \left[ \left( |w|^2 w - \frac{5KT}{m} w \right) \tilde{w} \right] B(\theta) d\theta d\epsilon d\tilde{v} \\ &= B_1 n f^{(0)} \left( -|w|^4 \delta + 3 |w|^2 w w + \frac{7KT}{m} |w|^2 \delta - \frac{21KT}{m} w w \right) \end{aligned} \quad (91)$$

$$\begin{aligned} & |w'|^2 |\tilde{w}'|^2 \tilde{w}' + |\tilde{w}'|^2 |w'|^2 w' - |w|^2 |\tilde{w}|^2 \tilde{w} - |\tilde{w}|^2 |w|^2 w \\ &= |w + \alpha(\alpha \cdot U)|^2 |\tilde{w} - \alpha(\alpha \cdot U)|^2 [\tilde{w} - \alpha(\alpha \cdot U)] + |\tilde{w} - \alpha(\alpha \cdot U)|^2 \\ & \quad \times |w + \alpha(\alpha \cdot U)|^2 [w + \alpha(\alpha \cdot U)] - |w|^2 |\tilde{w}|^2 (w + \tilde{w}) \\ &= (w + \tilde{w}) \{ (|w|^2 + |\tilde{w}|^2)(\alpha \cdot U)^2 + 2(\alpha \cdot U) \\ & \quad \times [(\alpha \cdot w) |\tilde{w}|^2 - (\alpha \cdot \tilde{w}) |w|^2] \\ & \quad - (\alpha \cdot U)^4 - 4(\alpha \cdot w)(\alpha \cdot \tilde{w})(\alpha \cdot U)^2 \} \end{aligned}$$

On account of formulas (43), (44) and the lemma in Section 6 we have

$$\begin{aligned} & \int d_c (|w|^2 |\tilde{w}|^2 \tilde{w}) d\epsilon \\ &= 2\pi \cos^2 \theta \sin^2 \theta [ |U|^4 + 6(U \cdot w)(U \cdot \tilde{w}) - 2|U|^2 (w \cdot \tilde{w}) ] (w + \tilde{w}) \\ &= 2\pi \cos^2 \theta \sin^2 \theta [ 2(w \cdot \tilde{w})^2 - 4|w|^2 |\tilde{w}|^2 + |w|^4 + |\tilde{w}|^4 ] (w + \tilde{w}) \end{aligned}$$

Hence,

$$\begin{aligned} & \int f^{(0)} \tilde{f}^{(0)} d_c (|w|^2 |\tilde{w}|^2 \tilde{w}) B(\theta) d\theta d\epsilon d\tilde{v} \\ &= 2B_1 n f^{(0)} \left[ |w|^4 w - 10 \frac{KT}{m} |w|^2 w + 15 \left( \frac{KT}{m} \right)^2 w \right] \end{aligned} \quad (92)$$

Combining formula (92) with formula (46) and Uhlenbeck and Wang-Chang's result about the eigenfunctions and eigenvalues of the linear Boltzmann integral operator, we have

$$\begin{aligned} & \int f^{(0)} \tilde{f}^{(0)} d_c \left[ \left( |w|^2 w - \frac{5KT}{m} w \right) \left( |\tilde{w}|^2 - \frac{3KT}{m} \right) \right] B(\theta) d\theta d\epsilon d\tilde{v} \\ &= 2B_1 n f^{(0)} \left[ |w|^4 w - \frac{14KT}{m} |w|^2 w + 35 \left( \frac{KT}{m} \right)^2 w \right] \end{aligned} \quad (93)$$

$$\begin{aligned}
 & |\tilde{w}'|^4 w' + |w'|^4 \tilde{w}' - |\tilde{w}|^4 w - |w|^4 \tilde{w} \\
 &= |\tilde{w} - \alpha(\alpha \cdot U)|^4 [w + \alpha(\alpha \cdot U)] \\
 &\quad + |w + \alpha(\alpha \cdot U)|^4 [\tilde{w} - \alpha(\alpha \cdot U)] - |\tilde{w}|^4 w - |w|^4 \tilde{w} \\
 &= (\alpha \cdot U)^4 (w + \tilde{w}) + 4(\alpha \cdot U)^2 [(\alpha \cdot \tilde{w})^2 w + (\alpha \cdot w)^2 \tilde{w}] \\
 &\quad + 2(\alpha \cdot U)^2 [|\tilde{w}|^2 w + |w|^2 \tilde{w}] + 4(\alpha \cdot U) [ |w|^2 (\alpha \cdot w) \tilde{w} - |\tilde{w}|^2 (\alpha \cdot \tilde{w}) w ] \\
 &\quad + 4(\alpha \cdot U)^3 [(\alpha \cdot w) \tilde{w} - (\alpha \cdot \tilde{w}) w] \\
 &\quad + (\alpha \cdot U) (|w|^2 + |\tilde{w}|^2) \{ |w|^2 - |\tilde{w}|^2 - 2(\alpha \cdot U) [\alpha \cdot (w + \tilde{w})] \} \alpha
 \end{aligned}$$

On account of formulas (43), (44) and the lemma in Section 6 we have

$$\begin{aligned}
 & \int d_c (|w|^4 \tilde{w}) d\epsilon \\
 &= -2\pi \cos^2 \theta \sin^2 \theta |U|^4 (w + \tilde{w}) + 4\pi \cos^2 \theta \sin^2 \theta |U|^2 (|\tilde{w}|^2 w + |w|^2 \tilde{w}) \\
 &\quad - 12\pi \cos^2 \theta \sin^2 \theta [(\tilde{w} \cdot U)^2 w + (w \cdot U)^2 \tilde{w}] \\
 &\quad - 8\pi \cos^2 \theta \sin^2 \theta |U|^2 [(U \cdot w) \tilde{w} - (U \cdot \tilde{w}) w] \\
 &\quad - 2\pi \cos^2 \theta \sin^2 \theta (|w|^2 + |\tilde{w}|^2) \{ |U|^2 (w + \tilde{w}) - 3[U \cdot (w + \tilde{w})] U \} \\
 &= \pi \cos^2 \theta \sin^2 \theta \{ [4|w|^2 |\tilde{w}|^2 - 10|\tilde{w}|^4 + 2|w|^4 - 4(w \cdot \tilde{w})^2 \\
 &\quad + 4(|w|^2 + |\tilde{w}|^2)(w \cdot \tilde{w})] w + [4|w|^2 |\tilde{w}|^2 - 10|w|^4 + 2|\tilde{w}|^4 - 4(w \cdot \tilde{w})^2 \\
 &\quad + 4(|w|^2 + |\tilde{w}|^2)(w \cdot \tilde{w})] \tilde{w} \}
 \end{aligned}$$

Hence,

$$\begin{aligned}
 & \int f^{(0)} \tilde{f}^{(0)} d_c (|w|^4 \tilde{w}) B(\theta) d\theta d\epsilon d\tilde{\epsilon} \\
 &= 2B_1 n f^{(0)} \left[ |w|^4 + 6 \frac{KT}{m} |w|^2 - 65 \left( \frac{KT}{m} \right)^2 \right] w \quad (94)
 \end{aligned}$$

On account of (94), (46) and the fact that  $w$  is a summational invariant, we have

$$\begin{aligned}
 & \int f^{(0)} \tilde{f}^{(0)} d_c \left\{ \left[ |w|^4 - 10 \frac{KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \tilde{w} \right\} B(\theta) d\theta d\epsilon d\tilde{\epsilon} \\
 &= 2B_1 n f^{(0)} \left[ |w|^4 - 14 \frac{KT}{m} |w|^2 + 35 \left( \frac{KT}{m} \right)^2 \right] w \quad (95)
 \end{aligned}$$

$$\begin{aligned}
 & |\tilde{w}'|^4|w'|^2 + |w'|^4|\tilde{w}'|^2 - |\tilde{w}'|^4|w|^2 - |w|^4|\tilde{w}'|^2 \\
 &= |\tilde{w}'|^2|w'|^2(|\tilde{w}'|^2 + |w'|^2) - |\tilde{w}'|^2|w|^2(|\tilde{w}'|^2 + |w|^2) \\
 &= (|\tilde{w}'|^2 + |w|^2)(|\tilde{w}'|^2|w'|^2 - |\tilde{w}'|^2|w|^2) \\
 &= (|\tilde{w}'|^2 + |w|^2)\{(|\tilde{w}'|^2 + |w|^2)(\alpha \cdot U)^2 \\
 &\quad + 2(\alpha \cdot U)[|\tilde{w}'|^2(\alpha \cdot w) - |w|^2(\alpha \cdot \tilde{w})] \\
 &\quad - (\alpha \cdot U)^4 - 4(\alpha \cdot U)^2(\alpha \cdot w)(\alpha \cdot \tilde{w})\}
 \end{aligned}$$

where we have used the equality immediately after equality (46).

On account of formulas (43), (44) and the lemma in Section 6, we have

$$\begin{aligned}
 & \int d_c(|w|^4|\tilde{w}'|^2) d\epsilon \\
 &= 2\pi \cos^2 \theta \sin^2 \theta [ |U|^4 - 2|U|^2(w \cdot \tilde{w}) + 6(U \cdot w)(U \cdot \tilde{w}) ] (|\tilde{w}'|^2 + |w|^2) \\
 &= 2\pi \cos^2 \theta \sin^2 \theta [ |w|^4 + |\tilde{w}'|^4 + 2(w \cdot \tilde{w})^2 - 4|w|^2|\tilde{w}'|^2 ] (|\tilde{w}'|^2 + |w|^2)
 \end{aligned}$$

Hence,

$$\begin{aligned}
 & \int f^{(0)}\tilde{f}^{(0)}d_c(|w|^4|\tilde{w}'|^2)B(\theta) d\theta d\epsilon d\tilde{v} \\
 &= 2B_1nf^{(0)}\left[ |w|^6 - \frac{7KT}{m}|w|^4 - 35\left(\frac{KT}{m}\right)^2|w|^2 + 105\left(\frac{KT}{m}\right)^3 \right] \quad (96)
 \end{aligned}$$

On account of (96), (47) and Uhlenbeck and Wang-Chang’s result about the eigenvalues and eigenfunctions of the linear Boltzmann integral operator, we have

$$\begin{aligned}
 & \int f^{(0)}\tilde{f}^{(0)}d_c\left\{ \left[ |w|^4 - \frac{10KT}{m}|w|^2 + 15\left(\frac{KT}{m}\right)^2 \right] \left( |\tilde{w}'|^2 - \frac{3K\tilde{T}}{m} \right) \right\} B(\theta) d\theta d\epsilon d\tilde{v} \\
 &= 2B_1nf^{(0)}\left[ |w|^6 - 21\frac{KT}{m}|w|^4 + 105\left(\frac{KT}{m}\right)^2|w|^2 - 105\left(\frac{KT}{m}\right)^3 \right] \quad (97)
 \end{aligned}$$

Substituting the results (45), (46), (47), (86), (89), (91), (93), (95), (97) and the Uhlenbeck–Wang-Chang results about the eigenvalues and eigenfunctions of the linear Boltzmann integral operator for the corresponding terms on the right-hand side of equation (83) and arranging the sum in a proper way, we have the following expression for  $J[h^{(2)}(z', \hat{z}, \tilde{z}') - h^{(2)}(z, \hat{z}, \tilde{z})]_{\tilde{x}=x}$ :

$$\begin{aligned}
 & J[h^{(2)}(z', \hat{z}, \tilde{z}') - h^{(2)}(z, \hat{z}, \tilde{z})]_{\tilde{x}=x} \\
 &= B_1 n f^{(0)} \hat{f}^{(0)} \left\{ \sum_{\substack{1 \leq i, s \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left( w_i w_s - \frac{1}{3} \delta_{is} |w|^2 \right) \right. \\
 &\quad \times \left[ -6a_{ij}(x, \hat{x}) a_{s0}(x, x) - \frac{18KT}{m} a_{ij}(x, \hat{x}) a_{s4}(x, x) + 3b_{ijs}(x, \hat{x}, x) \right] \\
 &\quad + \sum_{\substack{1 \leq i, s, t \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ w_i w_s w_t - \frac{1}{5} (w_i \delta_{st} + w_s \delta_{it} + w_t \delta_{is}) |w|^2 \right] \\
 &\quad \times \left[ 3a_{ij}(x, \hat{x}) a_{st}(x, x) \right] + \sum_{\substack{1 \leq i \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left( |w|^2 - \frac{5KT}{m} \right) \\
 &\quad \times w_i \left[ -\frac{2}{15} \sum_{1 \leq k < 3} a_{kj}(x, \hat{x}) a_{ki}(x, x) - \frac{2}{5} a_{ij}(x, \hat{x}) \sum_{1 \leq k < 3} a_{kk}(x, x) \right. \\
 &\quad \quad - 4a_{ij}(x, \hat{x}) a_{40}(x, x) - 4a_{4j}(x, \hat{x}) a_{i0}(x, x) \\
 &\quad \quad - \frac{12KT}{m} a_{ij}(x, \hat{x}) a_{44}(x, x) - \frac{12KT}{m} a_{4j}(x, \hat{x}) a_{i4}(x, x) \\
 &\quad \quad \left. + 4b_{ij4}(x, \hat{x}, x) \right] \\
 &\quad + \sum_{\substack{1 \leq i, s \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left( |w|^4 \delta_{is} - 3|w|^2 w_i w_s + \frac{21KT}{m} w_i w_s - 7|w|^2 \frac{KT}{m} \delta_{is} \right) \\
 &\quad \times \left[ -\frac{4}{3} a_{ij}(x, \hat{x}) a_{s4}(x, x) - a_{4j}(x, \hat{x}) a_{is}(x, x) \right] \\
 &\quad + \sum_{0 < j < 4} \hat{\psi}_j \left[ |w|^4 - 10 \frac{KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
 &\quad \times \left[ -4a_{4j}(x, \hat{x}) a_{40}(x, x) - \frac{12KT}{m} a_{4j}(x, \hat{x}) a_{44}(x, x) + 2b_{4j4}(x, \hat{x}, x) \right] \\
 &\quad + \sum_{\substack{1 \leq i \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ |w|^4 - 14|w|^2 \frac{KT}{m} + 35 \left( \frac{KT}{m} \right)^2 \right] \\
 &\quad \times w_i \left[ 2a_{ij}(x, \hat{x}) a_{44}(x, x) + 4a_{4j}(x, \hat{x}) a_{i4}(x, x) \right] =
 \end{aligned}$$

$$\begin{aligned}
& + \sum_{0 < j \leq 4} \hat{\psi}_j \left[ |w|^6 - 21|w|^4 \frac{KT}{m} + 105|w|^2 \left( \frac{KT}{m} \right)^2 - 105 \left( \frac{KT}{m} \right)^3 \right] \\
& \times 2a_{4j}(x, \hat{x}) a_{44}(x, x) + \sum_{1 \leq i, j, s, t \leq 3} \left( \hat{w}_i \hat{w}_s - \frac{|\hat{w}|^2}{3} \delta_{is} \right) \\
& \times \left( w_j w_t - \frac{|w|^2}{3} \delta_{jt} \right) 3a_{ij}(\hat{x}, x) a_{st}(\hat{x}, x) + \sum_{1 \leq i, j, s \leq 3} \left( \hat{w}_i \hat{w}_s - \frac{|\hat{w}|^2}{3} \delta_{is} \right) \\
& \times \left( |w|^2 - \frac{5KT}{m} \right) w_j 4a_{ij}(\hat{x}, x) a_{s4}(\hat{x}, x) + \sum_{1 \leq i, s \leq 3} \left( \hat{w}_i \hat{w}_s - \frac{|\hat{w}|^2}{3} \delta_{is} \right) \\
& \times \left[ |w|^4 - 10 \frac{KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] 2a_{i4}(\hat{x}, x) a_{s4}(\hat{x}, x) \\
& + \sum_{1 \leq i, j, t \leq 3} \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \hat{w}_i \left( w_j w_t - \frac{|w|^2}{3} \delta_{jt} \right) \\
& \times \left[ 3a_{ij}(\hat{x}, x) a_{4t}(\hat{x}, x) + 3a_{4j}(\hat{x}, x) a_{it}(\hat{x}, x) \right] \\
& + \sum_{1 \leq i, j \leq 3} \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \hat{w}_i \left( |w|^2 - \frac{5KT}{m} \right) \\
& \times w_j \left[ 4a_{ij}(\hat{x}, x) a_{44}(\hat{x}, x) + 4a_{4j}(\hat{x}, x) a_{i4}(\hat{x}, x) \right] \\
& + \sum_{1 \leq i \leq 3} \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \hat{w}_i \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] 4a_{i4}(\hat{x}, x) a_{44}(\hat{x}, x) \\
& + \sum_{1 \leq j, t \leq 3} \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \left( w_j w_t - \frac{|w|^2}{3} \delta_{jt} \right) \\
& \times 3a_{4j}(\hat{x}, x) a_{4t}(\hat{x}, x) + \sum_{1 \leq j \leq 3} \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \\
& \times \left( |w|^2 - \frac{5KT}{m} \right) w_j 4a_{4j}(\hat{x}, x) a_{44}(\hat{x}, x) + \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \\
& \times \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] 2 \left[ a_{44}(\hat{x}, x) \right]^2 \quad (98)
\end{aligned}$$

$J[h^{(2)}(z, \hat{z}', \tilde{z}') - h^{(2)}(z, \hat{z}, \tilde{z})]_{\tilde{x}=\hat{x}}$  has an expression similar to that on the right-hand side of (98). More precisely, the expression for  $J[h^{(2)}(z, \hat{z}', \tilde{z}') - h^{(2)}(z, \hat{z}, \tilde{z})]_{\tilde{x}=\hat{x}}$  can be obtained by exchanging  $z$  and  $\hat{z}$  in the expression on the right-hand side of (98).



11. THE CALCULATION OF  $[f^{(1)}g^{(1)}]_z$

On account of (34) and (50) we have

$$\begin{aligned}
 g^{(1)}(z, \hat{z}) f^{(1)}(\tilde{z}) &= f^{(0)} \hat{f}^{(0)} \tilde{f}^{(0)} \sum_{0 \leq j < 4} \hat{\psi}_j \sum_{0 \leq i < 4} a_{ij} \psi_i \left\{ \sum_{1 \leq s, t < 3} \left( \frac{\tilde{a}_{st}}{2} - \frac{m}{6B_1 \tilde{n} K \tilde{T}} \frac{\partial \tilde{u}_t}{\partial \tilde{x}_s} \right) \right. \\
 &\quad \times \left( \tilde{w}_s \tilde{w}_t - \frac{1}{3} |\tilde{w}|^2 \delta_{st} \right) \\
 &\quad + \sum_{1 \leq s < 3} \left( \tilde{a}_{s4} - \frac{m}{8B_1 n K \tilde{T}} \frac{\partial \tilde{T}}{\partial \tilde{x}_s} \right) \\
 &\quad \times \left( |\tilde{w}|^2 \tilde{w}_s - \frac{5K\tilde{T}}{m} \tilde{w}_s \right) \\
 &\quad \left. + \frac{\tilde{a}_{44}}{2} \left[ |\tilde{w}|^4 - 10 \frac{K\tilde{T}}{m} |\tilde{w}|^2 + 15 \left( \frac{K\tilde{T}}{m} \right)^2 \right] \right\} \tag{99}
 \end{aligned}$$

Using the formulas (86), (89), (91), (93), (95), (97), (99), and the results about the eigenfunctions and eigenvalues of the linear Boltzmann integral operator due to Uhlenbeck and Wang-Chang, we have

$$\begin{aligned}
 \mathcal{J}[f^{(1)}g^{(1)}]_z &= B_1 n f^{(0)} \hat{f}^{(0)} \left\{ \sum_{\substack{1 \leq i, s < 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left( w_i w_s - \frac{|w|^2}{3} \delta_{is} \right) \right. \\
 &\quad \times \left[ -6a_{0j}(x, \hat{x}) \left( \frac{a_{is}(x, x)}{2} - \frac{m}{6B_1 n K T} \frac{\partial u_s}{\partial x_i} \right) \right. \\
 &\quad \left. \left. - 18a_{4j}(x, \hat{x}) \left( \frac{a_{is}(x, x)}{2} - \frac{m}{6B_1 n K T} \frac{\partial u_s}{\partial x_i} \right) \frac{KT}{m} \right] \right. \\
 &\quad + \sum_{\substack{1 \leq i, s, t < 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left[ w_i w_s w_t - \frac{1}{5} (w_i \delta_{st} + w_s \delta_{it} + w_t \delta_{is}) |w|^2 \right] \\
 &\quad \times \left[ 3a_{ij}(x, \hat{x}) \left( \frac{a_{st}(x, x)}{2} - \frac{m}{6B_1 n K T} \frac{\partial u_s}{\partial x_t} \right) \right] \\
 &\quad \left. + \sum_{\substack{1 \leq i < 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left( |w|^2 - \frac{5KT}{m} \right) = \right.
 \end{aligned}$$

$$\begin{aligned}
& \times w_i \left[ \frac{2}{15} a_{ij}(x, \hat{x}) \left( \sum_{1 \leq k \leq 3} a_{kk}(x, x) - \frac{m}{3B_1 nKT} \sum_{1 \leq k \leq 3} \frac{\partial u_k}{\partial x_k} \right) \right. \\
& \quad - \frac{2}{5} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) \left[ a_{ik}(x, x) - \frac{m}{6B_1 nKT} \left( \frac{\partial u_k}{\partial x_i} + \frac{\partial u_i}{\partial x_k} \right) \right] \\
& \quad - 4a_{0j}(x, \hat{x}) \left( a_{i4} - \frac{m}{8B_1 nKT^2} \frac{\partial T}{\partial x_i} \right) \\
& \quad \left. - 12a_{4j}(x, \hat{x}) \left( a_{i4} - \frac{m}{8B_1 nKT^2} \frac{\partial T}{\partial x_i} \right) \frac{KT}{m} \right] \\
& + \sum_{\substack{1 \leq i, s \leq 3 \\ 0 \leq j \leq 4}} \hat{\psi}_j \left( |w|^4 \delta_{is} - 3|w|^2 w_i w_s + \frac{21KT}{m} w_i w_s - 7|w|^2 \frac{KT}{m} \delta_{is} \right) \\
& \times \left[ -\frac{1}{3} a_{4j}(x, \hat{x}) \left( \frac{a_{is}}{2} - \frac{m}{6B_1 nKT} \frac{\partial u_s}{\partial x_i} \right) - a_{ij}(x, \hat{x}) \left( a_{s4} - \frac{m}{8B_1 nKT^2} \frac{\partial T}{\partial x_s} \right) \right] \\
& + \sum_{0 \leq j \leq 4} \hat{\psi}_j \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
& \times \left[ -2a_{0j}(x, \hat{x}) a_{44}(x, x) - 6a_{4j}(x, \hat{x}) a_{44}(x, x) \frac{KT}{m} \right] \\
& + \sum_{\substack{1 \leq i \leq 3 \\ 0 \leq j \leq 4}} \hat{\psi}_j \left[ |w|^4 - 14|w|^2 \frac{KT}{m} + 35 \left( \frac{KT}{m} \right)^2 \right] \\
& \times w_i \left[ a_{ij}(x, \hat{x}) a_{44}(x, x) + 2a_{4j}(x, \hat{x}) \left( a_{i4} - \frac{m}{8B_1 nKT^2} \frac{\partial T}{\partial x_i} \right) \right] \\
& + \sum_{0 \leq j \leq 4} \hat{\psi}_j \left[ |w|^6 - 21|w|^4 \frac{KT}{m} + 105|w|^2 \left( \frac{KT}{m} \right)^2 - 105 \left( \frac{KT}{m} \right)^3 \right] \\
& \times a_{4j}(x, \hat{x}) a_{44}(x, x) \left. \right\} \tag{100}
\end{aligned}$$

The expression for  $\mathcal{F}[f^{(1)}g^{(1)}]_z$  can be obtained by exchanging  $z$  and  $\hat{z}$  in the expression on the right-hand side of (100).

**12. THE CALCULATION OF**  $\left(\frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k}\right)g^{(1)}$

The following formulas are easy to verify:

$$\left(\frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k}\right)\psi_0 = 0 \tag{101}$$

$$\left(\frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k}\right)\psi_i = \frac{K}{m} \frac{\partial T}{\partial x_i} + \frac{KT}{m} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} - w_k \frac{\partial u_i}{\partial x_k} \quad (1 \leq i \leq 3) \tag{102}$$

$$\left(\frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k}\right)\psi_4 = 2w_l \left(\frac{K}{m} \frac{\partial T}{\partial x_l} + \frac{KT}{m} \frac{1}{\rho} \frac{\partial \rho}{\partial x_l} - w_k \frac{\partial u_l}{\partial x_k}\right) \tag{103}$$

By virtue of (34), (41), (101), (102), and (103) we have

$$\begin{aligned} &\left(\frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k}\right)g^{(1)} \\ &= f^{(0)}\hat{f}^{(0)} \left\{ \sum_{\substack{0 \leq i, j \leq 4 \\ 1 \leq k \leq 3}} \frac{a_{ij}}{2T} \frac{\partial T}{\partial x_k} w_k \left(\frac{m|w|^2}{KT} - 5\right) \psi_i \hat{\psi}_j \right. \\ &\quad + \sum_{\substack{0 \leq i, j \leq 4 \\ 1 \leq k, l \leq 3}} \frac{m}{KT} \frac{\partial u_k}{\partial x_l} a_{ij} \left(w_k w_l - \frac{1}{3} |w|^2 \delta_{kl}\right) \psi_i \hat{\psi}_j \\ &\quad + \sum_{\substack{0 \leq i, j \leq 4 \\ 1 \leq k \leq 3}} \frac{a_{ij}}{2\hat{T}} \frac{\partial \hat{T}}{\partial \hat{x}_k} \hat{w}_k \left(\frac{m|\hat{w}|^2}{K\hat{T}} - 5\right) \psi_i \hat{\psi}_j \\ &\quad + \sum_{\substack{0 \leq i, j \leq 4 \\ 1 \leq k, l \leq 3}} \frac{m}{K\hat{T}} \frac{\partial \hat{u}_k}{\partial \hat{x}_l} a_{ij} \left(\hat{w}_k \hat{w}_l - \frac{1}{3} |\hat{w}|^2 \delta_{kl}\right) \psi_i \hat{\psi}_j \\ &\quad + \sum_{0 \leq i, j \leq 4} \left[ \left(\frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k}\right) a_{ij} \right] \psi_i \hat{\psi}_j \\ &\quad + \sum_{\substack{1 \leq j \leq 3 \\ 0 \leq i \leq 4}} a_{ij} \psi_i \left(\frac{K}{m} \frac{\partial \hat{T}}{\partial \hat{x}_j} + \frac{K\hat{T}}{m} \frac{1}{\hat{\rho}} \frac{\partial \hat{\rho}}{\partial \hat{x}_j} - \hat{w}_k \frac{\partial \hat{u}_j}{\partial \hat{x}_k}\right) \\ &\quad \left. + 2 \sum_{0 \leq i \leq 4} a_{i4} \psi_i \left(\frac{K}{m} \frac{\partial \hat{T}}{\partial \hat{x}_4} + \frac{K\hat{T}}{m} \frac{1}{\hat{\rho}} \frac{\partial \hat{\rho}}{\partial \hat{x}_4} - \hat{w}_l \frac{\partial \hat{u}_4}{\partial \hat{x}_l}\right) \hat{w}_4 = \right. \end{aligned}$$

$$\begin{aligned}
& + \sum_{\substack{1 \leq i \leq 3 \\ 0 < j < 4}} a_{ij} \hat{\psi}_j \left( \frac{K}{m} \frac{\partial T}{\partial x_i} + \frac{KT}{m} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} - w_k \frac{\partial u_i}{\partial x_k} \right) \\
& + 2 \sum_{0 \leq j < 4} a_{4j} \hat{\psi}_j \left( \frac{K}{m} \frac{\partial T}{\partial x_k} + \frac{KT}{m} \frac{1}{\rho} \frac{\partial \rho}{\partial x_k} - w_l \frac{\partial u_k}{\partial x_l} \right) w_k \left. \right\} \quad (104)
\end{aligned}$$

In order to get an explicit expression for

$$\left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) g^{(1)}$$

we have to calculate

$$\left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{ij} \quad (0 \leq i, j \leq 4)$$

A simple calculation shows us that

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{ij} \\
& = \left( w_k \frac{\partial}{\partial x_k} + \hat{w}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{ij} + \frac{2}{3} a_{ij} \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) - a_{kj} \frac{\partial u_i}{\partial x_k} - a_{ik} \frac{\partial \hat{u}_j}{\partial \hat{x}_k} \\
& \quad - \frac{\partial a_{i0}}{\partial \hat{x}_j} - \frac{\partial a_{0j}}{\partial x_i} - \frac{5K\hat{T}}{m} \frac{\partial a_{i4}}{\partial \hat{x}_j} - \frac{5KT}{m} \frac{\partial a_{4j}}{\partial x_i} - \frac{7K}{m} a_{i4} \frac{\partial \hat{T}}{\partial \hat{x}_j} - \frac{7K}{m} a_{4j} \frac{\partial T}{\partial x_i} \\
& \quad - \frac{2K\hat{T}}{m} a_{i4} \frac{1}{\hat{\rho}} \frac{\partial \hat{\rho}}{\partial \hat{x}_j} - \frac{2KT}{m} a_{4j} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} \quad (1 \leq i, j \leq 3) \quad (105)
\end{aligned}$$

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{i0} \\
& = \left( w_k \frac{\partial}{\partial x_k} + \hat{w}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{i0} + \frac{2}{3} a_{i0} \frac{\partial u_k}{\partial x_k} - a_{k0} \frac{\partial u_i}{\partial x_k} \\
& \quad - 2a_{40} \frac{KT}{m} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} + a_{ij} \left( \frac{3}{2} \frac{K}{m} \frac{\partial \hat{T}}{\partial \hat{x}_j} - \frac{K\hat{T}}{m} \frac{1}{\hat{\rho}} \frac{\partial \hat{\rho}}{\partial \hat{x}_j} \right) \\
& \quad - \left( \frac{\partial a_{00}}{\partial x_i} + \frac{5KT}{m} \frac{\partial a_{40}}{\partial x_i} + \frac{7K}{m} a_{40} \frac{\partial T}{\partial x_i} \right) \quad (1 \leq i \leq 3) \quad (106)
\end{aligned}$$

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{i4} \\
&= \left( w_k \frac{\partial}{\partial x_k} + \hat{w}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{i4} + \frac{2}{3} a_{i4} \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) - a_{k4} \frac{\partial u_i}{\partial x_k} \\
&\quad - \left( \frac{\partial a_{04}}{\partial x_i} + \frac{5KT}{m} \frac{\partial a_{44}}{\partial x_i} + \frac{7K}{m} a_{44} \frac{\partial T}{\partial x_i} \right) - \frac{1}{3} \frac{\partial a_{ik}}{\partial \hat{x}_k} - \frac{5}{6} a_{ik} \frac{1}{\hat{T}} \frac{\partial \hat{T}}{\partial \hat{x}_k} \\
&\quad - \frac{2KT}{m} a_{44} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} \quad (1 \leq i \leq 3) \tag{107}
\end{aligned}$$

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{00} \\
&= \left( w_k \frac{\partial}{\partial x_k} + \hat{w}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{00} + \frac{3K}{2m} \left( \frac{\partial T}{\partial x_k} a_{k0} + \frac{\partial \hat{T}}{\partial \hat{x}_k} a_{0k} \right) \\
&\quad - \frac{K}{m} \left( \frac{T}{\rho} \frac{\partial \rho}{\partial x_k} a_{k0} + \frac{\hat{T}}{\hat{\rho}} \frac{\partial \hat{\rho}}{\partial \hat{x}_k} a_{0k} \right) \tag{108}
\end{aligned}$$

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{04} \\
&= \left( w_k \frac{\partial}{\partial x_k} + \hat{w}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{04} + \frac{2}{3} a_{04} \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \\
&\quad + \frac{a_{k4}}{2} \left( \frac{3K}{m} \frac{\partial T}{\partial x_k} - \frac{2KT}{m} \frac{1}{\rho} \frac{\partial \rho}{\partial x_k} \right) - \frac{5}{6} a_{0k} \frac{1}{\hat{T}} \frac{\partial \hat{T}}{\partial \hat{x}_k} - \frac{1}{3} \frac{\partial a_{0k}}{\partial \hat{x}_k} \tag{109}
\end{aligned}$$

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{44} \\
&= \left( w_k \frac{\partial}{\partial x_k} + \hat{w}_k \frac{\partial}{\partial \hat{x}_k} \right) a_{44} + \frac{2}{3} a_{44} \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) - \frac{5}{6} a_{k4} \frac{1}{T} \frac{\partial T}{\partial x_k} \\
&\quad - \frac{5}{6} a_{4k} \frac{1}{\hat{T}} \frac{\partial \hat{T}}{\partial \hat{x}_k} - \frac{1}{3} \frac{\partial a_{k4}}{\partial x_k} - \frac{1}{3} \frac{\partial a_{4k}}{\partial \hat{x}_k} \tag{110}
\end{aligned}$$

Substituting the right-hand sides of the equalities (105), (106), (107), (108), (109), and (110) for the corresponding terms on the right-hand side of (104), we can get the following formula through an elementary, but slightly clumsy, calculation:

$$\begin{aligned}
& \left( \frac{\partial_0}{\partial t} + v_k \frac{\partial}{\partial x_k} + \hat{v}_k \frac{\partial}{\partial \hat{x}_k} \right) g^{(1)} \\
&= f^{(0)} \hat{f}^{(0)} \left\{ \sum_{\substack{1 \leq i, k \leq 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left( w w_k - \frac{\delta_{ik}}{3} |w|^2 \right) \right. \\
& \quad \times \left[ \frac{a_{ij}(x, \hat{x})}{T} \frac{\partial T}{\partial x_k} + \frac{m}{KT} a_{0j}(x, \hat{x}) \frac{\partial u_i}{\partial x_k} + 5a_{4j}(x, \hat{x}) \frac{\partial u_i}{\partial x_k} + \frac{\partial a_{ij}(x, \hat{x})}{\partial x_k} \right] \\
& \quad + \sum_{\substack{1 \leq i \leq 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left( |w|^2 - \frac{5KT}{m} \right) w_i \left[ \frac{m}{2KT^2} a_{0j}(x, \hat{x}) \frac{\partial T}{\partial x_i} + \frac{9a_{4j}(x, \hat{x})}{2T} \frac{\partial T}{\partial x_i} \right. \\
& \quad \quad \quad \left. - \frac{2m}{15KT} a_{ij}(x, \hat{x}) \sum_{1 \leq k \leq 3} \frac{\partial u_k}{\partial x_k} \right. \\
& \quad \quad \quad \left. + \frac{m}{5KT} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) + \frac{\partial a_{4j}(x, \hat{x})}{\partial x_i} \right] \\
& \quad + \sum_{\substack{1 \leq i, k, l \leq 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left[ w_i w_k w_l - \frac{1}{5} (w_i \delta_{kl} + w_k \delta_{il} + w_l \delta_{ik}) |w|^2 \right] \\
& \quad \times a_{ij}(x, \hat{x}) \frac{\partial u_k}{\partial x_l} \frac{m}{KT} + \sum_{0 \leq j < 4} \hat{\psi}_j \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
& \quad \times \frac{m}{6KT^2} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) \frac{\partial T}{\partial x_k} \\
& \quad + \sum_{\substack{1 \leq k, l \leq 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left( |w|^4 \delta_{kl} - 3|w|^2 w_k w_l - \frac{7KT}{m} |w|^2 \delta_{kl} + \frac{21KT}{m} w_k w_l \right) \\
& \quad \times \left[ -\frac{m}{6KT^2} a_{kj}(x, \hat{x}) \frac{\partial T}{\partial x_l} - \frac{m}{3KT} a_{4j}(x, \hat{x}) \frac{\partial u_k}{\partial x_l} \right] \\
& \quad + \sum_{\substack{1 \leq k \leq 3 \\ 0 \leq j < 4}} \hat{\psi}_j \left[ |w|^4 - 14|w|^2 \frac{KT}{m} + 35 \left( \frac{KT}{m} \right)^2 \right] \\
& \quad \times w_k \frac{m}{2KT^2} a_{4j}(x, \hat{x}) \frac{\partial T}{\partial x_k} \left. \right\}
\end{aligned}$$

+ the expression obtained from the above expression by exchanging  $z$  and  $\hat{z}$

(111)

## 13. THE SOLUTION OF EQUATION (31)

Substituting the right-hand sides of (98), (100), and (111) for the corresponding terms on the right-hand side of the equation (31), we have

$$\begin{aligned}
 & \mathcal{J}[f^{(0)}g^{(2)}]_z + \mathcal{J}[f^{(0)}g^{(0)}]_z \\
 &= B_1 n f^{(0)} \hat{f}^{(0)} \left[ \sum_{\substack{1 \leq i, k \leq 3 \\ 0 \leq j \leq 4}} \hat{\psi}_j \left( w_i w_k - \frac{\delta_{ik}}{3} |w|^2 \right) \right. \\
 & \times \left[ 6a_{ij}(x, \hat{x}) a_{k0}(x, x) + \frac{18KT}{m} a_{ij}(x, \hat{x}) a_{k4}(x, x) \right. \\
 & \quad + 3a_{0j}(x, \hat{x}) a_{ik}(x, x) + \frac{9KT}{m} a_{4j}(x, \hat{x}) a_{ik}(x, x) - 3b_{ijk}(x, \hat{x}, x) \\
 & \quad \left. \left. + \frac{a_{4j}(x, \hat{x})}{B_1 n} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) + \frac{1}{B_1 n T} \frac{\partial [Ta_{ij}(x, \hat{x})]}{\partial x_k} \right] \right] \\
 & + \sum_{\substack{1 \leq i \leq 3 \\ 0 \leq j \leq 4}} \hat{\psi}_j \left( |w|^2 - \frac{5KT}{m} \right) w_i \left[ \frac{8}{15} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) a_{ki}(x, x) \right. \\
 & + \frac{4}{15} a_{ij}(x, \hat{x}) \sum_{1 \leq k \leq 3} a_{kk}(x, x) + 4a_{ij}(x, \hat{x}) a_{40}(x, x) \\
 & + 4a_{4j}(x, \hat{x}) a_{i0}(x, x) + \frac{12KT}{m} a_{ij}(x, \hat{x}) a_{44}(x, x) \\
 & + \frac{24KT}{m} a_{4j}(x, \hat{x}) a_{i4}(x, x) + 4a_{0j}(x, \hat{x}) a_{i4}(x, x) \\
 & - 4b_{ij4}(x, \hat{x}, x) - \frac{4m}{45B_1 n KT} a_{ij}(x, \hat{x}) \sum_{1 \leq k \leq 3} \frac{\partial u_k}{\partial x_k} \\
 & + \frac{2m}{15B_1 n KT} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) + \frac{3}{B_1 n T} a_{4j}(x, \hat{x}) \frac{\partial T}{\partial x_i} \\
 & \left. \left. + \frac{1}{B_1 n} \frac{\partial a_{4j}(x, \hat{x})}{\partial x_i} \right] =
 \end{aligned}$$

$$\begin{aligned}
& + \sum_{\substack{1 \leq i, k, l \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ w_i w_k w_l - \frac{1}{5} (w_i \delta_{kl} + w_k \delta_{il} + w_l \delta_{ik}) |w|^2 \right] \\
& \times \left[ -\frac{9}{2} a_{ij}(x, \hat{x}) a_{kl}(x, x) + \frac{3m}{2B_1 nKT} a_{ij}(x, \hat{x}) \frac{\partial u_k}{\partial x_l} \right] \\
& + \sum_{0 < j < 4} \hat{\psi}_j \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
& \times \left[ 4a_{ij}(x, \hat{x}) a_{40}(x, x) + \frac{18KT}{m} a_{4j}(x, \hat{x}) a_{44}(x, x) + 2a_{0j}(x, \hat{x}) a_{44}(x, x) \right. \\
& \quad \left. - 2b_{4j4}(x, \hat{x}, x) + \frac{m}{6B_1 nKT^2} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) \frac{\partial T}{\partial x_k} \right] \\
& + \sum_{\substack{1 \leq k, l \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ |w|^4 \delta_{kl} - 3|w|^2 w_k w_l - \frac{7KT}{m} |w|^2 \delta_{kl} + \frac{21KT}{m} w_k w_l \right] \\
& \times \left[ \frac{7}{3} a_{kj}(x, \hat{x}) a_{l4}(x, x) + \frac{7}{6} a_{4j}(x, \hat{x}) a_{kl}(x, x) \right. \\
& \quad \left. - \frac{7m}{36B_1 nKT} a_{4j}(x, \hat{x}) \left( \frac{\partial u_k}{\partial x_l} + \frac{\partial u_l}{\partial x_k} \right) - \frac{7m}{24B_1 nKT^2} a_{kj}(x, \hat{x}) \frac{\partial T}{\partial x_l} \right] \\
& + \sum_{\substack{1 \leq k \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ |w|^4 - \frac{14KT}{m} |w|^2 + 35 \left( \frac{KT}{m} \right)^2 \right] \\
& \times w_k \left[ -3a_{kj}(x, \hat{x}) a_{44}(x, x) - 6a_{4j}(x, \hat{x}) a_{k4}(x, x) + \frac{3m}{4B_1 nKT^2} a_{4j}(x, \hat{x}) \frac{\partial T}{\partial x_k} \right] \\
& + \sum_{0 < j < 4} \hat{\psi}_j \left[ |w|^6 - \frac{21KT}{m} |w|^4 + 105 \left( \frac{KT}{m} \right)^2 |w|^2 - 105 \left( \frac{KT}{m} \right)^3 \right] \\
& \quad \left[ -3a_{4j}(x, \hat{x}) a_{44}(x, x) \right] \\
& + \sum_{1 \leq i, j, s, t \leq 3} \left( w_j w_i - \frac{1}{3} |w|^2 \delta_{jt} \right) \left( \hat{w}_i \hat{w}_s - \frac{1}{3} |\hat{w}|^2 \delta_{is} \right) \left[ -3a_{ij}(\hat{x}, x) a_{st}(\hat{x}, x) \right] =
\end{aligned}$$



$$\begin{aligned}
& + \sum_{1 \leq i, j, s \leq 3} \left( |w|^2 - \frac{5KT}{m} \right) w_j \left( \hat{w}_i \hat{w}_s - \frac{1}{3} |\hat{w}|^2 \delta_{is} \right) \left[ -4a_{ij}(\hat{x}, x) a_{s4}(\hat{x}, x) \right] \\
& + \sum_{1 \leq i, s \leq 3} \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
& \times \left( \hat{w}_i \hat{w}_s - \frac{1}{3} |\hat{w}|^2 \delta_{is} \right) \left[ -2a_{i4}(\hat{x}, x) a_{s4}(\hat{x}, x) \right] \\
& + \sum_{1 \leq i, j, t \leq 3} \left( w_j w_t - \frac{|w|^2}{3} \delta_{jt} \right) \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \hat{w}_i \left[ -6a_{ij}(\hat{x}, x) a_{4t}(\hat{x}, x) \right] \\
& + \sum_{1 \leq i, j \leq 3} \left( |w|^2 - \frac{5KT}{m} \right) w_j \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \\
& \times \hat{w}_i \left[ -4a_{ij}(\hat{x}, x) a_{44}(\hat{x}, x) - 4a_{4j}(\hat{x}, x) a_{i4}(\hat{x}, x) \right] \\
& + \sum_{1 \leq i \leq 3} \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \\
& \times \hat{w}_i \left[ -4a_{i4}(\hat{x}, x) a_{44}(\hat{x}, x) \right] + \sum_{1 \leq j, t \leq 3} \left( w_j w_t - \frac{1}{3} |w|^2 \delta_{jt} \right) \\
& \times \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \left[ -3a_{4j}(\hat{x}, x) a_{4t}(\hat{x}, x) \right] \\
& + \sum_{1 \leq j \leq 3} \left( |w|^2 - \frac{5KT}{m} \right) w_j \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \\
& \times \left[ -4a_{4j}(\hat{x}, x) a_{44}(\hat{x}, x) \right] + \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
& \times \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \left\{ -2[a_{44}(\hat{x}, x)]^2 \right\} \\
& + \text{the expression obtained from the above one by exchanging } z \text{ and } \hat{z}
\end{aligned}$$

(112)

Wang-Chang and Uhlenbeck<sup>(2)</sup> have found all the eigenfunctions with their corresponding eigenvalues for the linear Boltzmann integral operator.

Some of them, which we shall use in the sequel, are listed as follows:

<i>Eigenfunctions</i>	<i>The corresponding eigenvalues</i>
$f^{(0)}$	0
$f^{(0)} w_i \quad (1 \leq i \leq 3)$	0
$f^{(0)}  w ^2$	0
$f^{(0)} \left( w_i w_j - \frac{1}{3}  w ^2 \delta_{ij} \right) \quad (1 \leq i, j \leq 3)$	$-6B_1 n$
$f^{(0)} \left(  w ^2 - \frac{5KT}{m} \right) w_i \quad (1 \leq i \leq 3)$	$-4B_1 n$
$f^{(0)} \left[ w_i w_j w_k - \frac{1}{5} (w_i \delta_{jk} + w_j \delta_{ik} + w_k \delta_{ij})  w ^2 \right]$ $(1 \leq i, j, k \leq 3)$	$-9B_1 n$
$f^{(0)} \left[  w ^4 - 10 \frac{KT}{m}  w ^2 + 15 \left( \frac{KT}{m} \right)^2 \right]$	$-4B_1 n$
$f^{(0)} \left(  w ^4 \delta_{ij} - 3  w ^2 w_i w_j - 7 \frac{KT}{m}  w ^2 \delta_{ij} + 21 \frac{KT}{m} w_i w_j \right)$ $(1 \leq i, j \leq 3)$	$-7B_1 n$
$f^{(0)} \left[  w ^4 - 14 \frac{KT}{m}  w ^2 + 35 \left( \frac{KT}{m} \right)^2 \right] w_i$ $(1 \leq i \leq 3)$	$-6B_1 n$
$f^{(0)} \left[  w ^6 - 21 \frac{KT}{m}  w ^4 + 105 \left( \frac{KT}{m} \right)^2  w ^2 - 105 \left( \frac{KT}{m} \right)^3 \right]$	$-6B_1 n$

Each tensor product of two eigenfunctions of the linear Boltzmann integral operator is an eigenfunction of the linear Boltzmann double-integral operator with the sum of two corresponding eigenvalues as its own eigenvalue. For instance,

$$\begin{aligned} & \mathcal{J} \left[ f^{(0)} \hat{f}^{(0)} \tilde{f}^{(0)} \left( w_i w_j - \frac{1}{3} |w|^2 \delta_{ij} \right) \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \hat{w}_k \right]_z \\ & \quad + \mathcal{J} \left[ f^{(0)} \hat{f}^{(0)} \tilde{f}^{(0)} \left( w_i w_j - \frac{1}{3} |w|^2 \delta_{ij} \right) \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) w_k \right]_z \\ & = (-6B_1 n - 4B_1 \hat{n}) f^{(0)} \hat{f}^{(0)} \left( w_i w_j - \frac{1}{3} |w|^2 \delta_{ij} \right) \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \hat{w}_k \end{aligned}$$

Using the above facts, we find a solution of equation (112) as follows:

$$\begin{aligned}
 g^{(2)} = f^{(0)} \hat{f}^{(0)} & \left\{ \sum_{\substack{1 \leq i, k \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left( w_i w_k - \frac{1}{3} \delta_{ik} |w|^2 \right) \right. \\
 & \times \left[ -a_{ij}(x, \hat{x}) a_{k0}(x, x) - \frac{3KT}{m} a_{ij}(x, \hat{x}) a_{k4}(x, x) - \frac{1}{2} a_{0j}(x, \hat{x}) a_{ik}(x, x) \right. \\
 & \quad - \frac{3KT}{2m} a_{4j}(x, \hat{x}) a_{ik}(x, x) + \frac{1}{2} b_{ijk}(x, \hat{x}, x) \\
 & \quad \left. - \frac{a_{4j}(x, \hat{x})}{6B_1 n} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) - \frac{1}{6B_1 n T} \frac{\partial [T a_{ij}(x, \hat{x})]}{\partial x_k} \right] \\
 & + \sum_{\substack{1 \leq i \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left( |w|^2 - \frac{5KT}{m} \right) \\
 & \times w_i \left[ -\frac{2}{15} \sum_{1 \leq k < 3} a_{kj}(x, \hat{x}) a_{ki}(x, x) - \frac{1}{15} a_{ij}(x, \hat{x}) \sum_{1 \leq k < 3} a_{kk}(x, x) \right. \\
 & \quad - a_{ij}(x, \hat{x}) a_{40}(x, x) - a_{4j}(x, \hat{x}) a_{i0}(x, x) - \frac{3KT}{m} a_{ij}(x, \hat{x}) a_{44}(x, x) \\
 & \quad - \frac{6KT}{m} a_{4j}(x, \hat{x}) a_{i4}(x, x) + b_{ij4}(x, \hat{x}, x) + \frac{m}{45B_1 n KT} a_{ij}(x, \hat{x}) \\
 & \quad \times \sum_{1 \leq k < 3} \frac{\partial u_k}{\partial x_k} - \frac{m}{30B_1 n KT} \sum_{1 \leq k < 3} a_{kj}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\
 & \quad \left. - a_{0j}(x, \hat{x}) a_{i4}(x, x) - \frac{3}{4B_1 n T} a_{4j}(x, \hat{x}) \frac{\partial T}{\partial x_i} - \frac{1}{4B_1 n} \frac{\partial a_{4j}(x, \hat{x})}{\partial x_i} \right] \\
 & + \sum_{\substack{1 \leq i, k, l \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ w_i w_k w_l - \frac{1}{5} (w_i \delta_{kl} + w_k \delta_{il} + w_l \delta_{ik}) |w|^2 \right] \\
 & \times \left[ \frac{1}{2} a_{ij}(x, \hat{x}) a_{kl}(x, x) - \frac{m}{6B_1 n KT} a_{ij}(x, \hat{x}) \frac{\partial u_x}{\partial x_l} \right] =
 \end{aligned}$$

$$\begin{aligned}
 & + \sum_{0 < j \leq 4} \hat{\psi}_j \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
 & \times \left[ -a_{4j}(x, \hat{x}) a_{40}(x, x) - \frac{9KT}{2m} a_{4j}(x, \hat{x}) a_{44}(x, x) - \frac{1}{2} a_{0j}(x, \hat{x}) a_{44}(x, x) \right. \\
 & \quad \left. + \frac{1}{2} b_{4j4}(x, \hat{x}, x) - \frac{m}{24B_1 nKT^2} \sum_{1 \leq k \leq 3} a_{kj}(x, \hat{x}) \frac{\partial T}{\partial x_k} \right] \\
 & + \sum_{\substack{1 \leq k, l \leq 3 \\ 0 < j < 4}} \hat{\psi}_j \left[ |w|^4 \delta_{kl} - 3|w|^2 w_k w_l - \frac{7KT}{m} |w|^2 \delta_{kl} + \frac{21KT}{m} w_k w_l \right] \\
 & \times \left[ -\frac{1}{3} a_{kj}(x, \hat{x}) a_{l4}(x, x) - \frac{1}{6} a_{4j}(x, \hat{x}) a_{kl}(x, x) \right. \\
 & \quad \left. + \frac{m}{36B_1 nKT} a_{4j}(x, \hat{x}) \left( \frac{\partial u_k}{\partial x_l} + \frac{\partial u_l}{\partial x_k} \right) + \frac{m}{24B_1 nKT^2} a_{kj}(x, x) \frac{\partial T}{\partial x_l} \right] \\
 & + \sum_{\substack{1 \leq k \leq 3 \\ 0 < j \leq 4}} \hat{\psi}_j \left[ |w|^4 - \frac{14KT}{m} |w|^2 + 35 \left( \frac{KT}{m} \right)^2 \right] \\
 & \times w_k \left[ \frac{1}{2} a_{kj}(x, \hat{x}) a_{44}(x, x) + a_{4j}(x, \hat{x}) a_{k4}(x, x) - \frac{m}{8B_1 nKT^2} a_{4j}(x, \hat{x}) \frac{\partial T}{\partial x_k} \right] \\
 & + \sum_{0 < j \leq 4} \hat{\psi}_j \left[ |w|^6 - 21 \frac{KT}{m} |w|^4 + 105 \left( \frac{KT}{m} \right)^2 |w|^2 - 105 \left( \frac{KT}{m} \right)^3 \right] \\
 & \times \left[ \frac{1}{2} a_{4j}(x, \hat{x}) a_{44}(x, x) \right] \\
 & + \text{the expression obtained from the above expression by exchanging} \\
 & \quad z \text{ and } \hat{z} \\
 & + \sum_{1 \leq i, j, s, t \leq 3} \left( w_j w_t - \frac{1}{3} |w|^2 \delta_{jt} \right) \left( \hat{w}_i \hat{w}_s - \frac{1}{3} |\hat{w}|^2 \delta_{is} \right) \frac{1}{2} a_{ij}(\hat{x}, x) a_{st}(\hat{x}, x) \\
 & + \sum_{1 \leq i, j, s \leq 3} \left( |w|^2 - \frac{5KT}{m} \right) w_j \left( \hat{w}_i \hat{w}_s - \frac{|\hat{w}|^2}{3} \delta_{is} \right) a_{ij}(\hat{x}, x) a_{s4}(\hat{x}, x) \\
 & + \sum_{1 \leq i, s \leq 3} \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \left( \hat{w}_i \hat{w}_s - \frac{1}{3} |\hat{w}|^2 \delta_{is} \right) \\
 & \times \frac{1}{2} a_{i4}(\hat{x}, x) a_{s4}(\hat{x}, x) + \sum_{1 \leq i, j, t \leq 3} \left( w_j w_t - \frac{|w|^2}{3} \delta_{jt} \right) \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) =
 \end{aligned}$$

$$\begin{aligned}
 & \times \hat{w}_i a_{ij}(\hat{x}, x) a_{4i}(\hat{x}, x) + \sum_{1 \leq i, j \leq 3} \left( |w|^2 - \frac{5KT}{m} \right) w_i \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \\
 & \times \hat{w}_i [a_{ij}(\hat{x}, x) a_{44}(\hat{x}, x) + a_{4j}(\hat{x}, x) a_{i4}(\hat{x}, x)] \\
 & + \sum_{1 \leq i \leq 3} \left[ |w|^4 - 10 \frac{KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \left( |\hat{w}|^2 - \frac{5K\hat{T}}{m} \right) \\
 & \times \hat{w}_i [a_{i4}(\hat{x}, x) a_{44}(\hat{x}, x)] + \sum_{1 \leq j, l \leq 3} \left( w_j w_l - \frac{|w|^2}{3} \delta_{jl} \right) \\
 & \times \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \frac{1}{2} a_{4j}(\hat{x}, x) a_{4l}(\hat{x}, x) \\
 & + \sum_{1 \leq j \leq 3} \left( |w|^2 - \frac{5KT}{m} \right) w_j \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \\
 & \times a_{4j}(\hat{x}, x) a_{44}(\hat{x}, x) + \left[ |w|^4 - \frac{10KT}{m} |w|^2 + 15 \left( \frac{KT}{m} \right)^2 \right] \\
 & \times \left[ |\hat{w}|^4 - \frac{10K\hat{T}}{m} |\hat{w}|^2 + 15 \left( \frac{K\hat{T}}{m} \right)^2 \right] \frac{1}{2} [a_{44}(\hat{x}, x)]^2 \} \tag{113}
 \end{aligned}$$

Obviously the above solution satisfies the additional integral conditions.

#### 14. APPROXIMATE EQUATIONS OF ORDER $1 \frac{2}{3}$ FOR TURBULENT FLOWS

The summation convention will be used throughout this section. On account of (72) we have the following equalities:

$$\begin{aligned}
 S_{ij}^{(2,0,0)(0)} &= \frac{1}{n} \left[ R_i^{(1,0)}(x, \hat{x}) R_j^{(1,0)}(x, \check{x}) + R_j^{(1,0)}(x, \hat{x}) R_i^{(1,0)}(x, \check{x}) \right] \\
 &+ \frac{\delta_{ij}}{3} \left[ S^{(2,0,0)} - \frac{1}{n} R_k^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right] \\
 S_{ij,k}^{(2,1,0)(0)} &= \frac{1}{n} \left[ R_{i,k}^{(1,1)}(x, \hat{x}) R_j^{(1,0)}(x, \check{x}) + R_{j,k}^{(1,1)}(x, \hat{x}) R_i^{(1,0)}(x, \check{x}) \right] \\
 &+ \frac{\delta_{ij}}{3} \left[ S^{(2,1,0)} - \frac{2}{n} R_{l,k}^{(1,1)}(x, \hat{x}) R_l^{(1,0)}(x, \check{x}) \right] =
 \end{aligned}$$

$$S_{ij,k,l}^{(2,1,1)(0)} = \frac{1}{n} \left[ R_{i,k}^{(1,1)}(x, \hat{x}) R_{j,l}^{(1,1)}(x, \check{x}) + R_{j,k}^{(1,1)}(x, \hat{x}) R_{i,l}^{(1,1)}(x, \check{x}) \right] \\ + \frac{\delta_{ij}}{3} \left[ S_{k,l}^{(2,1,1)} - \frac{2}{n} R_{m,k}^{(1,1)}(x, \hat{x}) R_{m,l}^{(1,1)}(x, \check{x}) \right]$$

$$S_{ij}^{(2,2,0)(0)} = \frac{1}{n} \left[ R_i^{(1,2)}(x, \hat{x}) R_j^{(1,0)}(x, \check{x}) + R_j^{(1,2)}(x, \hat{x}) R_i^{(1,0)}(x, \check{x}) \right] \\ + \frac{\delta_{ij}}{3} \left[ S^{(2,2,0)} - \frac{2}{n} R_k^{(1,2)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right]$$

$$S_{ij,k}^{(2,2,1)(0)} = \frac{1}{n} \left[ R_i^{(1,2)}(x, \hat{x}) R_{j,k}^{(1,1)}(x, \check{x}) + R_j^{(1,2)}(x, \hat{x}) R_{i,k}^{(1,1)}(x, \check{x}) \right] \\ + \frac{\delta_{ij}}{3} \left[ S_{k}^{(2,2,1)} - \frac{2}{n} R_l^{(1,2)}(x, \hat{x}) R_{l,k}^{(1,1)}(x, \check{x}) \right]$$

$$S_{ij}^{(2,2,2)(0)} = \frac{1}{n} \left[ R_i^{(1,2)}(x, \hat{x}) R_j^{(1,2)}(x, \check{x}) + R_j^{(1,2)}(x, \hat{x}) R_i^{(1,2)}(x, \check{x}) \right] \\ + \frac{\delta_{ij}}{3} \left[ S^{(2,2,2)} - \frac{2}{n} R_k^{(1,2)}(x, \hat{x}) R_k^{(1,2)}(x, \check{x}) \right]$$

$$S_i^{(3,0,0)(0)} = \frac{5KT}{m} S_i^{(1,0,0)} \\ + \frac{5}{3n} \left[ R_i^{(1,0)}(x, \hat{x}) \left( R^{(2,0)}(x, \check{x}) - \frac{3KT}{m} R^{(0,0)}(x, \check{x}) \right) \right. \\ \left. + R_i^{(1,0)}(x, \check{x}) \left( R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right) \right]$$

$$S_{ij}^{(3,1,0)(0)} = \frac{5KT}{m} S_{ij}^{(1,1,0)} \\ + \frac{5}{3n} \left[ R_{ij}^{(1,2)}(x, \hat{x}) \left( R^{(2,0)}(x, \check{x}) - \frac{3KT}{m} R^{(0,0)}(x, \check{x}) \right) \right. \\ \left. + R_i^{(1,0)}(x, \check{x}) \left( R_j^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) \right) \right]$$

$$S_{ij,k}^{(3,1,1)(0)} = \frac{5KT}{m} S_{ij,k}^{(1,1,1)} \\ + \frac{5}{3n} \left[ R_{ij}^{(1,1)}(x, \hat{x}) \left( R_k^{(2,1)}(x, \check{x}) - \frac{3KT}{m} R_k^{(0,1)}(x, \check{x}) \right) \right. \\ \left. + R_{i,k}^{(1,1)}(x, \check{x}) \left( R_j^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) \right) \right]$$

$$S_{i,j}^{(3,2,1)(0)} = \frac{5KT}{m} S_{i,j}^{(1,2,1)} + \frac{5}{3n} \left[ R_{i}^{(1,2)}(x, \hat{x}) \left( R^{(2,1)}(x, \check{x}) - \frac{3KT}{m} R^{(0,1)}(x, \check{x}) \right) + R_{ij}^{(1,1)}(x, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \right]$$

$$S_i^{(3,2,0)(0)} = \frac{5KT}{m} S_i^{(1,2,0)} + \frac{5}{3n} \left[ R_{i}^{(1,2)}(x, \hat{x}) \left( R^{(2,0)}(x, \check{x}) - \frac{3KT}{m} R^{(0,0)}(x, \check{x}) \right) + R_i^{(1,0)}(x, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \right]$$

$$S_i^{(3,2,2)(0)} = \frac{5KT}{m} S_i^{(1,2,2)} + \frac{5}{3n} \left[ R_{i}^{(1,2)}(x, \hat{x}) \left( R^{(2,2)}(x, \check{x}) - \frac{3KT}{m} R^{(0,2)}(x, \check{x}) \right) + R_i^{(1,2)}(x, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \right]$$

Substituting the right-hand sides of the above equalities for the corresponding  $S$ 's in the conservation equations, we get the following 125 approximate equations governing the evolution of 125  $S$ 's:

$$\frac{\Delta S^{(0,0,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(0,0,0)} + \frac{\partial S_k^{(1,0,0)}}{\partial x_k} + \frac{\partial S_k^{(0,1,0)}}{\partial \hat{x}_k} + \frac{\partial S^{(0,0,1)}}{\partial \check{x}_k} = 0 \tag{114}$$

$$\begin{aligned} \frac{\Delta S_i^{(1,0,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_i^{(1,0,0)} + \frac{Du_i}{Dt} S^{(0,0,0)} \\ + S_k^{(1,0,0)} \frac{\partial u_i}{\partial x_k} + \frac{\partial S_{i,k}^{(1,1,0)}}{\partial \hat{x}_k} + \frac{\partial S_{i,k}^{(1,0,1)}}{\partial \check{x}_k} \\ + \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_i^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) + R_k^{(1,0)}(x, \hat{x}) R_i^{(1,0)}(x, \check{x}) \right] \right\} \\ + \frac{1}{3} \frac{\partial}{\partial x_i} \left[ S^{(2,0,0)} - \frac{2}{n} R_k^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right] = 0 \end{aligned} \tag{115}$$

(1 ≤ i ≤ 3)

$$\begin{aligned}
& \frac{\Delta S_{ij}^{(1,1,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_{ij}^{(1,1,0)} + \frac{Du_i}{Dt} S_j^{(0,1,0)} \\
& + \frac{\hat{D}\hat{u}_j}{\hat{D}t} S_i^{(1,0,0)} + \frac{\partial u_i}{\partial x_k} S_{kj}^{(1,1,0)} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S_{ik}^{(1,1,0)} \\
& + \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_{ij}^{(1,1)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) + R_{kj}^{(1,1)}(x, \hat{x}) R_i^{(1,0)}(x, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial x_i} \left[ S_j^{(2,1,0)} - \frac{2}{n} R_{kj}^{(1,1)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right] \\
& + \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R_{ij}^{(1,1)}(x, \hat{x}) R_k^{(1,0)}(\hat{x}, \check{x}) + R_{ik}^{(1,1)}(x, \hat{x}) R_j^{(1,0)}(\hat{x}, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left[ S_i^{(1,2,0)} - \frac{2}{\hat{n}} R_{ik}^{(1,1)}(x, \hat{x}) R_k^{(1,0)}(\hat{x}, \check{x}) \right] + \frac{\partial S_{ijk}^{(1,1,1)}}{\partial \check{x}_k} = 0 \\
& \qquad \qquad \qquad (1 \leq i, j \leq 3) \quad (116)
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta S_{ijl}^{(1,1,1)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_{ijl}^{(1,1,1)} + \frac{Du_i}{Dt} S_{jl}^{(0,1,1)} \\
& + \frac{\hat{D}\hat{u}_j}{\hat{D}t} S_{il}^{(1,0,1)} + \frac{\check{D}\check{u}_l}{\check{D}t} S_{ij}^{(1,1,0)} + \frac{\partial u_i}{\partial x_k} S_{ijl}^{(1,1,1)} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S_{ikl}^{(1,1,1)} \\
& + \frac{\partial \check{u}_l}{\partial \check{x}_k} S_{ij,k}^{(1,1,1)} + \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_{ij}^{(1,1)}(x, \hat{x}) R_{kl}^{(1,1)}(x, \check{x}) \right. \right. \\
& \qquad \qquad \qquad \left. \left. + R_{kj}^{(1,1)}(x, \hat{x}) R_{il}^{(1,1)}(x, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial x_i} \left[ S_{jl}^{(2,1,1)} - \frac{2}{n} R_{kj}^{(1,1)}(x, \hat{x}) R_{kl}^{(1,1)}(x, \check{x}) \right] \\
& + \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R_{ik}^{(1,1)}(x, \hat{x}) R_{jl}^{(1,1)}(\hat{x}, \check{x}) + R_{ij}^{(1,1)}(x, \hat{x}) R_{kl}^{(1,1)}(\hat{x}, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left[ S_{il}^{(1,2,1)} - \frac{2}{\hat{n}} R_{ik}^{(1,1)}(x, \hat{x}) R_{kl}^{(1,1)}(\hat{x}, \check{x}) \right] \\
& + \frac{\partial}{\partial \check{x}_k} \left\{ \frac{1}{\check{n}} \left[ R_{ik}^{(1,1)}(x, \check{x}) R_{jl}^{(1,1)}(\hat{x}, \check{x}) + R_{il}^{(1,1)}(x, \check{x}) R_{jk}^{(1,1)}(\hat{x}, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \check{x}_l} \left[ S_{ij}^{(1,1,2)} - \frac{2}{\check{n}} R_{ik}^{(1,1)}(x, \check{x}) R_{jk}^{(1,1)}(\hat{x}, \check{x}) \right] = 0 \\
& \qquad \qquad \qquad (1 \leq i, j, l \leq 3) \quad (117)
\end{aligned}$$



$$\begin{aligned}
 & \frac{\Delta S^{(2,0,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,0,0)} + 2S_k^{(1,0,0)} \frac{Du_k}{Dt} \\
 & + 2 \frac{\partial u_k}{\partial x_s} \frac{1}{n} \left[ R_k^{(1,0)}(x, \hat{x}) R_s^{(1,0)}(x, \check{x}) + R_s^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right] \\
 & + \frac{2}{3} \left( \frac{\partial u_k}{\partial x_k} \right) \left[ S^{(2,0,0)} - \frac{2}{n} R_k^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right] \\
 & + \frac{5K}{m} \frac{\partial}{\partial x_k} (TS_k^{(1,0,0)}) \\
 & + \frac{5}{3} \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_k^{(1,0)}(x, \hat{x}) \left( R^{(2,0)}(x, \check{x}) - \frac{3KT}{m} R^{(0,0)}(x, \check{x}) \right) \right. \right. \\
 & \quad \left. \left. + R_k^{(1,0)}(x, \check{x}) \left( R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right) \right] \right\} \\
 & + \frac{\partial S_k^{(2,1,0)}}{\partial \hat{x}_k} + \frac{\partial S_k^{(2,0,1)}}{\partial \check{x}_k} = 0 \tag{118}
 \end{aligned}$$

$$\begin{aligned}
 & \frac{\Delta S_j^{(2,1,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S_j^{(2,1,0)} + 2S_{kj}^{(1,1,0)} \frac{Du_k}{Dt} \\
 & + S^{(2,0,0)} \frac{\hat{D}\hat{u}_j}{\hat{D}t} + \frac{2}{n} \frac{\partial u_k}{\partial x_s} \left[ R_{kj}^{(1,1)}(x, \hat{x}) R_s^{(1,0)}(x, \check{x}) \right. \\
 & \quad \left. + R_{sj}^{(1,1)}(x, \hat{x}) R_k^{(1,0)}(x, \check{x}) \right] \\
 & + \frac{2}{3} \left( \frac{\partial u_k}{\partial x_k} \right) \left[ S_j^{(2,1,0)} - \frac{2}{n} R_{lj}^{(1,1)}(x, \hat{x}) R_l^{(1,0)}(x, \check{x}) \right] \\
 & + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S_k^{(2,1,0)} + \frac{5K}{m} \frac{\partial}{\partial x_k} (TS_{kj}^{(1,1,0)}) \\
 & + \frac{5}{3} \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_{kj}^{(1,1)}(x, \hat{x}) \left( R^{(2,0)}(x, \check{x}) - \frac{3KT}{m} R^{(0,0)}(x, \check{x}) \right) \right. \right. \\
 & \quad \left. \left. + R_k^{(1,0)}(x, \check{x}) \left( R_j^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) \right) \right] \right\} \\
 & + \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{n} \left[ R_k^{(2,1)}(x, \hat{x}) R_j^{(1,0)}(\hat{x}, \check{x}) + R_j^{(2,1)}(x, \hat{x}) R_k^{(1,0)}(\hat{x}, \check{x}) \right] \right\} \\
 & + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left[ S^{(2,2,0)} - \frac{2}{n} R_k^{(2,1)}(x, \hat{x}) R_k^{(1,0)}(\hat{x}, \check{x}) \right] + \frac{\partial S_{j,k}^{(2,1,1)}}{\partial \check{x}_k} = 0 \\
 & \tag{1 \leq j \leq 3} \tag{119}
 \end{aligned}$$

$$\begin{aligned}
& \frac{\Delta S_{j,l}^{(2,1,1)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,1,1)} + 2 \frac{Du_k}{Dt} S_{k,j,l}^{(1,1,1)} \\
& + \frac{\hat{D}\hat{u}_j}{\hat{D}t} S^{(2,0,1)} + \frac{\check{D}\check{u}_l}{\check{D}t} S^{(2,1,0)} + \frac{2}{n} \frac{\partial u_k}{\partial x_s} \left[ R_{k,j}^{(1,1)}(x, \hat{x}) R_{s,l}^{(1,1)}(x, \check{x}) \right. \\
& \qquad \qquad \qquad \left. + R_{s,j}^{(1,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(x, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial u_k}{\partial x_k} \right) \left[ S^{(2,1,1)} - \frac{1}{n} R_{mj}^{(1,1)}(x, \hat{x}) R_{m,l}^{(1,1)}(x, \check{x}) \right] \\
& + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S^{(2,1,1)} + \frac{\partial \check{u}_l}{\partial \check{x}_k} S^{(2,1,1)} + \frac{5K}{m} \frac{\partial}{\partial x_k} (TS_{k,j,l}^{(1,1,1)}) \\
& + \frac{5}{3} \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_{k,j}^{(1,1)}(x, \hat{x}) \left( R_l^{(2,1)}(x, \check{x}) - \frac{3KT}{m} R_l^{(0,1)}(x, \check{x}) \right) \right. \right. \\
& \qquad \qquad \qquad \left. \left. + R_{k,l}^{(1,1)}(x, \check{x}) \left( R_k^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_k^{(0,1)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R_k^{(2,1)}(x, \hat{x}) R_{j,l}^{(1,1)}(\hat{x}, \check{x}) + R_j^{(2,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(\hat{x}, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left[ S^{(2,2,1)} - \frac{2}{\hat{n}} R_k^{(2,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(\hat{x}, \check{x}) \right] \\
& + \frac{\partial}{\partial \check{x}_k} \left\{ \frac{1}{\check{n}} \left[ R_k^{(2,1)}(x, \check{x}) R_{j,l}^{(1,1)}(\hat{x}, \check{x}) + R_l^{(2,1)}(x, \check{x}) R_{j,k}^{(1,1)}(\hat{x}, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \check{x}_l} \left[ S^{(2,1,2)} - \frac{2}{\check{n}} R_k^{(2,1)}(x, \check{x}) R_{j,k}^{(1,1)}(\hat{x}, \check{x}) \right] = 0 \\
& \qquad \qquad \qquad (1 \leq j, l \leq 3) \quad (120)
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta S_{l}^{(2,2,1)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,2,1)} + 2 \frac{Du_k}{Dt} S_{k,l}^{(1,2,1)} \\
& + 2 \frac{\hat{D}\hat{u}_k}{\hat{D}t} S_{k,l}^{(2,1,1)} + \frac{\check{D}\check{u}_l}{\check{D}t} S^{(2,2,0)} + \frac{2}{n} \frac{\partial u_k}{\partial x_s} \\
& \times \left[ R_k^{(1,2)}(x, \hat{x}) R_{s,l}^{(1,1)}(x, \check{x}) + R_s^{(1,2)}(x, \hat{x}) R_{k,l}^{(1,1)}(x, \check{x}) \right] + \frac{1}{3} \left( \frac{\partial u_k}{\partial x_k} \right) \\
& \times \left[ S^{(2,2,1)} - \frac{1}{n} R_m^{(1,2)}(x, \hat{x}) R_{m,l}^{(1,1)}(x, \check{x}) \right] =
\end{aligned}$$

$$\begin{aligned}
& + \frac{2}{\hat{n}} \frac{\partial \hat{u}_k}{\partial \hat{x}_s} \left[ R^{(2,1)}_k(x, \hat{x}) R^{(1,1)}_{s,l}(\hat{x}, \check{x}) + R^{(2,1)}_s(x, \hat{x}) R^{(1,1)}_{k,l}(\hat{x}, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) \left[ S^{(2,2,1)} - \frac{2}{\hat{n}} R^{(2,1)}_m(x, \hat{x}) R^{(1,1)}_{m,l}(\hat{x}, \check{x}) \right] \\
& + \frac{\partial \check{u}_l}{\partial \check{x}_k} S^{(2,2,1)}_k + \frac{5K}{m} \frac{\partial}{\partial \check{x}_k} (TS^{(1,2,1)}_{k,l}) \\
& + \frac{5}{3} \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R^{(1,2)}_k(x, \hat{x}) \left( R^{(2,1)}_l(x, \check{x}) - \frac{3KT}{m} R^{(0,1)}_l(x, \check{x}) \right) + R^{(1,1)}_{k,l}(x, \check{x}) \right. \right. \\
& \quad \left. \left. \times \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \right] \right\} + \frac{5K}{m} \frac{\partial}{\partial \hat{x}_k} (\hat{T}S^{(2,1,1)}_{k,l}) \\
& + \frac{5}{3} \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R^{(2,1)}_k(x, \hat{x}) \left( R^{(2,1)}_l(\hat{x}, \check{x}) - \frac{3K\hat{T}}{m} R^{(0,1)}_l(\hat{x}, \check{x}) \right) \right. \right. \\
& \quad \left. \left. + R^{(1,1)}_{k,l}(\hat{x}, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{\partial}{\partial \check{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R^{(2,1)}_k(x, \check{x}) R^{(2,1)}_l(\hat{x}, \check{x}) + R^{(2,1)}_l(x, \check{x}) R^{(2,1)}_k(\hat{x}, \check{x}) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \check{x}_l} \left[ S^{(2,2,2)} - \frac{2}{\hat{n}} R^{(2,1)}_k(x, \check{x}) R^{(2,1)}_k(\hat{x}, \check{x}) \right] = 0 \quad (1 \leq l \leq 3) \quad (121)
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta S^{(2,2,0)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,2,0)} + 2 \frac{Du_k}{Dt} S^{(1,2,0)}_k + 2 \frac{\hat{D}\hat{u}_k}{\hat{D}t} S^{(2,1,0)}_k \\
& + \frac{2}{n} \frac{\partial u_k}{\partial x_s} \left[ R^{(1,2)}_k(x, \hat{x}) R^{(1,0)}_s(x, \check{x}) + R^{(1,2)}_s(x, \hat{x}) R^{(1,0)}_k(x, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial u_k}{\partial x_k} \right) \left[ S^{(2,2,0)} - \frac{2}{n} R^{(1,2)}_l(x, \hat{x}) R^{(1,0)}_l(x, \check{x}) \right] \\
& + \frac{2}{\hat{n}} \frac{\partial \hat{u}_k}{\partial \hat{x}_s} \left[ R^{(2,1)}_k(x, \hat{x}) R^{(1,0)}_s(\hat{x}, \check{x}) + R^{(2,1)}_s(x, \hat{x}) R^{(1,0)}_k(\hat{x}, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) \left[ S^{(2,2,0)} - \frac{2}{\hat{n}} R^{(2,1)}_l(x, \hat{x}) R^{(1,0)}_l(\hat{x}, \check{x}) \right] \\
& + \frac{5K}{m} \frac{\partial}{\partial x_k} (TS^{(1,2,0)}_k) \\
& + \frac{5}{3} \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R^{(1,2)}_k(x, \hat{x}) \left( R^{(2,0)}(x, \check{x}) - \frac{3KT}{m} R^{(0,0)}(x, \check{x}) \right) \right. \right.
\end{aligned}$$

$$\begin{aligned}
& + R_k^{(1,0)}(x, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \Big] + \frac{5K}{m} \frac{\partial}{\partial \hat{x}_k} (\hat{T} S_k^{(2,1,0)}) \\
& + \frac{5}{3} \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R_k^{(2,1)}(x, \hat{x}) \left( R^{(2,0)}(\hat{x}, \check{x}) - \frac{3K\hat{T}}{m} R^{(0,0)}(\hat{x}, \check{x}) \right) \right. \right. \\
& \quad \left. \left. + R_k^{(1,0)}(\hat{x}, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{\partial S_k^{(2,2,1)}}{\partial \check{x}_k} = 0 \tag{122}
\end{aligned}$$

$$\begin{aligned}
& \frac{\Delta S^{(2,2,2)}}{\Delta t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} + \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) S^{(2,2,2)} + 2 \frac{Du_k}{Dt} S_k^{(1,2,2)} \\
& + 2 \frac{\hat{D}\hat{u}_k}{\hat{D}t} S^{(2,1,2)} + 2 \frac{\check{D}\check{u}_k}{\check{D}t} S^{(2,2,1)} \\
& + \frac{2}{n} \frac{\partial u_k}{\partial x_s} \left[ R_k^{(1,2)}(x, \hat{x}) R_s^{(1,2)}(x, \check{x}) + R_s^{(1,2)}(x, \hat{x}) R_k^{(1,2)}(x, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial u_k}{\partial x_k} \right) \left[ S^{(2,2,2)} - \frac{2}{n} R_l^{(1,2)}(x, \hat{x}) R_l^{(1,2)}(x, \check{x}) \right] \\
& + \frac{2}{\hat{n}} \frac{\partial \hat{u}_k}{\partial \hat{x}_s} \left[ R_k^{(2,1)}(x, \hat{x}) R_s^{(1,2)}(\hat{x}, \check{x}) + R_s^{(2,1)}(x, \hat{x}) R_k^{(1,2)}(\hat{x}, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) \left[ S^{(2,2,2)} - \frac{2}{\hat{n}} R_l^{(2,1)}(x, \hat{x}) R_l^{(1,2)}(\hat{x}, \check{x}) \right] \\
& + \frac{2}{\check{n}} \frac{\partial \check{u}_k}{\partial \check{x}_s} \left[ R_k^{(2,1)}(x, \check{x}) R_s^{(2,1)}(\hat{x}, \check{x}) + R_s^{(2,1)}(x, \check{x}) R_k^{(2,1)}(\hat{x}, \check{x}) \right] \\
& + \frac{2}{3} \left( \frac{\partial \check{u}_k}{\partial \check{x}_k} \right) \left[ S^{(2,2,2)} - \frac{2}{\check{n}} R_l^{(2,1)}(x, \check{x}) R_l^{(2,1)}(\hat{x}, \check{x}) \right] \\
& + \frac{5K}{m} \frac{\partial}{\partial x_k} (TS_k^{(1,2,2)}) \\
& + \frac{5}{3} \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} \left[ R_k^{(1,2)}(x, \hat{x}) \left( R^{(2,2)}(x, \check{x}) - \frac{3KT}{m} R^{(0,2)}(x, \check{x}) \right) \right. \right. \\
& \quad \left. \left. + R_k^{(1,2)}(x, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{5K}{m} \frac{\partial}{\partial \hat{x}_k} (\hat{T} S_k^{(2,1,2)}) \\
& + \frac{5}{3} \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} \left[ R_k^{(2,1)}(x, \hat{x}) \left( R^{(2,2)}(\hat{x}, \check{x}) - \frac{3K\hat{T}}{m} R^{(0,2)}(\hat{x}, \check{x}) \right) \right. \right.
\end{aligned}$$

$$\begin{aligned}
 &+ R_k^{(1,2)}(\hat{x}, \check{x}) \left( R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right) \Big] + \frac{5K}{m} \frac{\partial}{\partial \check{x}_k} (\check{T} S^{(2,2,1)_k}) \\
 &+ \frac{5}{3} \frac{\partial}{\partial \check{x}_k} \left\{ \frac{1}{\check{n}} \left[ R_k^{(2,1)}(x, \check{x}) \left( R^{(2,2)}(\hat{x}, \check{x}) - \frac{3K\check{T}}{m} R^{(2,0)}(\hat{x}, \check{x}) \right) \right. \right. \\
 &\quad \left. \left. + R_k^{(2,1)}(\hat{x}, \check{x}) \left( R^{(2,2)}(x, \check{x}) - \frac{3K\check{T}}{m} R^{(2,0)}(x, \check{x}) \right) \right] \right\} = 0
 \end{aligned}
 \tag{123}$$

Equations (114)–(123) represent 125 equations which, together with the 30 equations represented by (53)–(61), form a system of approximate equations governing the motion of turbulent flows. We call this system the approximate equation system of order  $1\frac{1}{3}$  for turbulent flows. Since the 125  $S$ 's do not appear in (53)–(61), we can solve equations (53)–(61) independently. This fact makes the approximate system of equations of order  $1\frac{1}{3}$  mathematically insignificant.

On account of (113) and the result for the zeroth-order approximation of the  $R$ 's, we have

$$\begin{aligned}
 &R_{ik}^{(2,0)(0)} + R_{ik}^{(2,0)(1)} \\
 &= \frac{1}{n^2} \left\{ nS_{i,k}^{(1,0,1)}(x, \hat{x}, x) - R_{i,k}^{(1,1)}(x, x) R^{(0,0)}(x, \hat{x}) \right. \\
 &\quad - R_i^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, x) - R_k^{(1,0)}(x, \hat{x}) R_i^{(1,0)}(x, x) \\
 &\quad - \frac{n}{18B_1} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \left[ R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right] \\
 &\quad - \frac{n^2KT}{6B_1m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R_i^{(1,0)}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R_k^{(1,0)}(x, \hat{x}) \right) \right] \\
 &\quad + \frac{\delta_{ik}}{3} \left[ n^2 R^{(2,0)}(x, \hat{x}) - \left( nS_{i,l}^{(1,0,1)}(x, \hat{x}, x) - R^{(0,0)}(x, \hat{x}) R_{l,i}^{(1,1)}(x, x) \right. \right. \\
 &\quad \quad - 2R_l^{(1,0)}(x, \hat{x}) R_l^{(1,0)}(x, x) \\
 &\quad \quad - \frac{n}{9B_1} \left( \frac{\partial u_l}{\partial x_l} \right) \left( R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right) \\
 &\quad \quad \left. \left. - \frac{n^2KT}{3B_1m} \frac{\partial}{\partial x_l} \left( \frac{1}{n} R_l^{(1,0)}(x, \hat{x}) \right) \right) \right] \Big\} =
 \end{aligned}$$

$$\begin{aligned}
& R_{ikj}^{(2,1)(0)} + R_{ikj}^{(2,1)(1)} \\
&= \frac{1}{n^2} \left\{ nS_{ij,k}^{(1,1,1)}(x, \hat{x}, x) - R_{i,k}^{(1,1)}(x, x) R_j^{(0,1)}(x, \hat{x}) \right. \\
&\quad - R_{ij}^{(1,1)}(x, \hat{x}) R_k^{(1,0)}(x, x) - R_{kj}^{(1,1)}(x, \hat{x}) R_i^{(1,0)}(x, x) \\
&\quad - \frac{n}{18B_1} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \left[ R_j^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) \right] \\
&\quad - \frac{n^2KT}{6B_1m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R_{ij}^{(1,1)}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R_{kj}^{(1,1)}(x, \hat{x}) \right) \right] \\
&\quad + \frac{\delta_{ik}}{3} \left[ n^2 R_j^{(2,1)}(x, \hat{x}) - \left( nS_{ij,l}^{(1,1,1)}(x, \hat{x}, x) \right. \right. \\
&\quad \quad - R_j^{(0,1)}(x, \hat{x}) R_{l,l}^{(1,1)}(x, x) - 2R_{ij}^{(1,1)}(x, \hat{x}) R_l^{(1,0)}(x, x) \\
&\quad \quad - \frac{n}{9B_1} \left( R_j^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) \right) \left( \frac{\partial u_l}{\partial x_i} \right) \\
&\quad \quad \left. \left. - \frac{n^2KT}{3B_1m} \frac{\partial}{\partial x_l} \left( \frac{1}{n} R_{ij}^{(1,1)}(x, \hat{x}) \right) \right) \right] \left. \right\}
\end{aligned}$$

$$\begin{aligned}
& R_{ik}^{(2,2)(0)} + R_{ik}^{(2,2)(1)} \\
&= \frac{1}{n^2} \left\{ nS_{i,k}^{(1,2,1)}(x, \hat{x}, x) - R_{i,k}^{(1,1)}(x, x) R^{(0,2)}(x, \hat{x}) \right. \\
&\quad - R_i^{(1,2)}(x, \hat{x}) R_k^{(1,0)}(x, x) - R_k^{(1,2)}(x, \hat{x}) R_i^{(1,0)}(x, x) \\
&\quad - \frac{n}{18B_1} \left( \frac{\partial u_i}{\partial x_i} + \frac{\partial u_k}{\partial x_i} \right) \left[ R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right] \\
&\quad - \frac{n^2KT}{6B_1m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R_i^{(1,2)}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R_k^{(1,2)}(x, \hat{x}) \right) \right] \\
&\quad + \frac{\delta_{ik}}{3} \left[ n^2 R^{(2,2)}(x, \hat{x}) - \left( nS_{l,l}^{(1,2,1)}(x, \hat{x}, x) - R^{(0,2)}(x, \hat{x}) R_{l,l}^{(1,1)}(x, x) \right. \right. \\
&\quad \quad \left. \left. - 2R_l^{(1,2)}(x, \hat{x}) R_l^{(1,0)}(x, x) = \right. \right.
\end{aligned}$$

$$\left. \begin{aligned} & - \frac{n}{9B_1} \left( \frac{\partial u_l}{\partial x_l} \right) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \\ & - \frac{n^2KT}{3B_1m} \frac{\partial}{\partial x_l} \left( \frac{1}{n} R^{(1,2)}(x, \hat{x}) \right) \end{aligned} \right\}$$

$$R_i^{(3,0)(0)} + R_i^{(3,0)(1)}$$

$$\begin{aligned} &= \frac{1}{n^2} \left\{ - \frac{4}{3} R_k^{(1,0)}(x, \hat{x}) R_{k,i}^{(1,1)}(x, x) - \frac{2}{3} R_i^{(1,0)}(x, \hat{x}) R_{k,k}^{(1,1)}(x, x) \right. \\ & \quad + \frac{5}{3} R_i^{(1,0)}(x, \hat{x}) \left[ \frac{3KT}{m} R^{(0,0)}(x, x) - R^{(0,2)}(x, x) \right] \\ & \quad + \frac{5}{3} R_i^{(1,0)}(x, x) \left[ \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) - R^{(2,0)}(x, \hat{x}) \right] \\ & \quad + \frac{5}{3} R^{(0,0)}(x, \hat{x}) \left[ \frac{3KT}{m} R_i^{(1,0)}(x, x) - R_i^{(1,2)}(x, x) \right] \\ & \quad + \frac{5n}{3} \left[ S_i^{(1,0,2)}(x, \hat{x}, x) - \frac{3KT}{m} S_i^{(1,0,0)}(x, \hat{x}, x) \right] \\ & \quad + \frac{2KTn}{9B_1m} \left( \frac{\partial u_k}{\partial x_k} \right) R_i^{(1,0)}(x, \hat{x}) - \frac{KTn}{3B_1m} R_k^{(1,0)}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\ & \quad - \frac{5Kn}{6B_1m} \left( R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right) \frac{\partial T}{\partial x_i} \\ & \quad - \frac{5Kn^2T^2}{12B_1m} \frac{\partial}{\partial x_i} \left[ \frac{1}{nT} R^{(2,0)}(x, \hat{x}) - \frac{3K}{mn} R^{(0,0)}(x, \hat{x}) \right] \left. \right\} \\ & \quad + \frac{5KT}{m} R_i^{(1,0)}(x, \hat{x}) \end{aligned}$$

$$R_{ij}^{(3,1)(0)} + R_{ij}^{(3,1)(1)}$$

$$\begin{aligned} &= \frac{1}{n^2} \left\{ - \frac{4}{3} R_{kj}^{(1,1)}(x, \hat{x}) R_{k,i}^{(1,1)}(x, x) - \frac{2}{3} R_{ij}^{(1,1)}(x, \hat{x}) R_{k,k}^{(1,1)}(x, x) \right. \\ & \quad + \frac{5}{3} R_{ij}^{(1,1)}(x, \hat{x}) \left[ \frac{3KT}{m} R^{(0,0)}(x, x) - R^{(0,2)}(x, x) \right] \\ & \quad + \frac{5}{3} R_i^{(1,0)}(x, x) \left[ \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) - R_j^{(2,1)}(x, \hat{x}) \right] = \end{aligned}$$

$$\begin{aligned}
& + \frac{5}{3} R_j^{(0,1)}(x, \hat{x}) \left[ \frac{3KT}{m} R_i^{(1,0)}(x, x) - R_i^{(1,2)}(x, x) \right] \\
& + \frac{5n}{3} \left[ S_{ij}^{(1,1,2)}(x, \hat{x}, x) - \frac{3KT}{m} S_{ij}^{(1,1,0)}(x, \hat{x}, x) \right] \\
& + \frac{2KTn}{9B_1m} \left( \frac{\partial u_k}{\partial x_k} \right) R_{ij}^{(1,1)}(x, \hat{x}) - \frac{KTn}{3B_1m} R_{kj}^{(1,1)}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\
& - \frac{5Kn}{6B_1m} \left( R_j^{(2,1)}(x, \hat{x}) - \frac{3KT}{m} R_j^{(0,1)}(x, \hat{x}) \right) \frac{\partial T}{\partial x_i} \\
& - \frac{5Kn^2T^2}{12B_1m} \frac{\partial}{\partial x_i} \left[ \frac{1}{nT} R_j^{(2,1)}(x, \hat{x}) - \frac{3K}{mn} R_j^{(0,1)}(x, \hat{x}) \right] \Big\} \\
& + \frac{5KT}{m} R_{ij}^{(1,1)}(x, \hat{x}) \\
R_i^{(3,2)(0)} + R_i^{(3,2)(1)} \\
& = \frac{1}{n^2} \left\{ - \frac{4}{3} R_k^{(1,2)}(x, \hat{x}) R_{k,i}^{(1,1)}(x, x) - \frac{2}{3} R_i^{(1,2)}(x, \hat{x}) R_{k,k}^{(1,1)}(x, x) \right. \\
& + \frac{5}{3} R_i^{(1,2)}(x, \hat{x}) \left[ \frac{3KT}{m} R^{(0,0)}(x, x) - R^{(0,2)}(x, x) \right] \\
& + \frac{5}{3} R_i^{(1,0)}(x, x) \left[ \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) - R^{(2,2)}(x, \hat{x}) \right] \\
& + \frac{5}{3} R^{(0,2)}(x, \hat{x}) \left[ \frac{3KT}{m} R_i^{(1,0)}(x, x) - R_i^{(1,2)}(x, x) \right] \\
& + \frac{5n}{3} \left[ S_{i}^{(1,2,2)}(x, \hat{x}, x) - \frac{3KT}{m} S_{i}^{(1,2,0)}(x, \hat{x}, x) \right] \\
& + \frac{2KTn}{9B_1m} \left( \frac{\partial u_k}{\partial x_k} \right) R_i^{(1,2)}(x, \hat{x}) - \frac{KTn}{3B_1m} R_k^{(1,2)}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\
& - \frac{5Kn}{6B_1m} \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \frac{\partial T}{\partial x_i} \\
& - \frac{5Kn^2T^2}{12B_1m} \frac{\partial}{\partial x_i} \left[ \frac{1}{nT} R^{(2,2)}(x, \hat{x}) - \frac{3K}{mn} R^{(0,2)}(x, \hat{x}) \right] \Big\} \\
& + \frac{5KT}{m} R_i^{(1,2)}(x, \hat{x})
\end{aligned}$$



Now we can make a new closure of the conservation equations (20)–(25) as follows:

$$\begin{aligned} & \frac{\mathcal{D} R^{(0,0)}}{\mathcal{D} t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) R^{(0,0)} + \frac{\partial R^{(1,0)}_k}{\partial x_k} + \frac{\partial R^{(0,1)}_k}{\partial \hat{x}_k} = 0 \quad (124) \\ & \frac{\mathcal{D} R^{(1,0)}_i}{\mathcal{D} t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) R^{(1,0)}_i + \frac{D u_i}{D t} R^{(0,0)} + R^{(1,0)}_k \frac{\partial u_i}{\partial x_k} \\ & + \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} S^{(1,0,1)}_{i,k}(x, \hat{x}, x) - \frac{1}{n^2} R^{(1,1)}_{i,k}(x, x) R^{(0,0)}(x, \hat{x}) \right. \\ & \quad - \frac{1}{n^2} R^{(1,0)}_i(x, \hat{x}) R^{(1,0)}_k(x, x) - \frac{1}{n^2} R^{(1,0)}_k(x, \hat{x}) R^{(1,0)}_i(x, x) \\ & \quad - \frac{1}{18 B_1 n} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \left[ R^{(2,0)}(x, \hat{x}) - \frac{3 K T}{m} R^{(0,0)}(x, \hat{x}) \right] \\ & \quad \left. - \frac{K T}{6 B_1 m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R^{(1,0)}_i(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R^{(1,0)}_k(x, \hat{x}) \right) \right] \right\} \\ & + \frac{1}{3} \frac{\partial}{\partial x_i} \left\{ R^{(2,0)}(x, \hat{x}) - \left[ \frac{1}{n} S^{(1,0,1)}_{i,l}(x, \hat{x}, x) - \frac{R^{(0,0)}(x, \hat{x})}{n^2} \right. \right. \\ & \quad \times R^{(1,1)}_{i,l}(x, x) - \frac{2}{n^2} R^{(1,0)}_l(x, \hat{x}) R^{(1,0)}_i(x, x) - \frac{1}{9 B_1 n} \\ & \quad \times \left( \frac{\partial u_i}{\partial x_l} \right) \left( R^{(2,0)}(x, \hat{x}) - \frac{3 K T}{m} R^{(0,0)}(x, \hat{x}) \right) - \frac{K T}{3 B_1 m} \frac{\partial}{\partial x_l} \\ & \quad \left. \left. \times \left( \frac{1}{n} R^{(1,0)}_l(x, \hat{x}) \right) \right] \right\} + \frac{\partial R^{(1,1)}_{i,k}}{\partial \hat{x}_k} = 0 \quad (1 \leq i \leq 3) \quad (125) \\ & \frac{\mathcal{D} R^{(1,1)}_{ij}}{\mathcal{D} t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) R^{(1,1)}_{ij} + \frac{D u_i}{D t} R^{(0,1)}_j + \frac{\hat{D} \hat{u}_j}{\hat{D} t} R^{(1,0)}_i \\ & + R^{(1,1)}_{kj} \frac{\partial u_i}{\partial x_k} + R^{(1,1)}_{i,k} \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} S^{(1,1,1)}_{ij,k}(x, \hat{x}, x) \right. \\ & \quad - \frac{1}{n^2} R^{(1,1)}_{i,k}(x, x) R^{(0,1)}_j(x, \hat{x}) - \frac{1}{n^2} R^{(1,1)}_{ij}(x, \hat{x}) R^{(1,0)}_k(x, x) \\ & \quad \left. - \frac{1}{n^2} R^{(1,1)}_{kj}(x, \hat{x}) R^{(1,0)}_i(x, x) - \frac{1}{18 B_1 n} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) = \right. \end{aligned}$$

$$\begin{aligned}
& \times \left[ R^{(2,j)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,j)}(x, \hat{x}) \right] \\
& - \frac{KT}{6B_1 m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R^{(1,1)}_{ij}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R^{(1,1)}_{kj}(x, \hat{x}) \right) \right] \Bigg\} \\
& + \frac{1}{3} \frac{\partial}{\partial x_i} \left\{ R^{(2,j)}(x, \hat{x}) - \left[ \frac{1}{n} S^{(1,1,1)}_{ij,l}(x, \hat{x}, x) - \frac{1}{n^2} R^{(0,j)}(x, \hat{x}) R^{(1,1)}_{i,l}(x, x) \right. \right. \\
& \quad \left. \left. - \frac{2}{n^2} R^{(1,1)}_{ij}(x, \hat{x}) R^{(1,0)}_i(x, x) - \frac{1}{9B_1 n} \left( \frac{\partial u_l}{\partial x_l} \right) \right. \right. \\
& \quad \left. \left. \times \left( R^{(2,j)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,j)}(x, \hat{x}) \right) - \frac{KT}{3B_1 m} \frac{\partial}{\partial x_l} \left( \frac{1}{n} R^{(1,1)}_{ij}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} S^{(1,1,1)}_{ij,k}(x, \hat{x}, \hat{x}) - \frac{1}{\hat{n}^2} R^{(1,1)}_{kj}(\hat{x}, \hat{x}) R^{(1,0)}_i(x, \hat{x}) \right. \\
& \quad \left. - \frac{1}{\hat{n}^2} R^{(1,1)}_{ij}(x, \hat{x}) R^{(1,0)}_k(\hat{x}, \hat{x}) - \frac{1}{\hat{n}^2} R^{(1,1)}_{i,k}(x, \hat{x}) R^{(1,0)}_j(\hat{x}, \hat{x}) \right. \\
& \quad \left. - \frac{1}{18B_1 \hat{n}} \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) \left[ R^{(1,2)}_i(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(1,0)}_i(x, \hat{x}) \right] \right. \\
& \quad \left. - \frac{K\hat{T}}{6B_1 m} \left[ \frac{\partial}{\partial \hat{x}_k} \left( \frac{1}{\hat{n}} R^{(1,1)}_{ij}(x, \hat{x}) \right) + \frac{\partial}{\partial \hat{x}_j} \left( \frac{1}{\hat{n}} R^{(1,1)}_{i,k}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left\{ R^{(1,2)}_i(x, \hat{x}) - \left[ \frac{1}{\hat{n}} S^{(1,1,1)}_{i,l,l}(x, \hat{x}, \hat{x}) \right. \right. \\
& \quad \left. \left. - \frac{1}{\hat{n}^2} R^{(1,0)}_i(x, \hat{x}) R^{(1,1)}_{l,l}(\hat{x}, \hat{x}) - \frac{2}{\hat{n}^2} R^{(1,1)}_{i,l}(x, \hat{x}) R^{(1,0)}_l(\hat{x}, \hat{x}) \right. \right. \\
& \quad \left. \left. - \frac{1}{9B_1 \hat{n}} \left( \frac{\partial \hat{u}_l}{\partial \hat{x}_l} \right) \left( R^{(1,2)}_i(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(1,0)}_i(x, \hat{x}) \right) \right. \right. \\
& \quad \left. \left. - \frac{K\hat{T}}{3B_1 m} \frac{\partial}{\partial \hat{x}_l} \left( \frac{1}{\hat{n}} R^{(1,1)}_{i,l}(x, \hat{x}) \right) \right] \right\} = 0 \quad (1 \leq i, j \leq 3) \quad (126)
\end{aligned}$$

$$\begin{aligned}
& \frac{\mathcal{D}}{\mathcal{D}t} R^{(2,0)} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) R^{(2,0)} + 2 \frac{Du_i}{Dt} R^{(1,0)} \\
& + \frac{2}{n^2} \frac{\partial u_i}{\partial x_k} \left\{ n S^{(1,0,1)}_{i,k}(x, \hat{x}, x) - R^{(1,1)}_{i,k}(x, x) R^{(0,0)}(x, \hat{x}) = \right.
\end{aligned}$$

$$\begin{aligned}
& - R_i^{(1,0)}(x, \hat{x}) R_k^{(1,0)}(x, x) - R_k^{(1,0)}(x, \hat{x}) R_i^{(1,0)}(x, x) \\
& - \frac{n}{18B_1} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \left[ R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right] \\
& - \frac{n^2KT}{6B_1m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R_i^{(1,0)}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R_k^{(1,0)}(x, \hat{x}) \right) \right] \Bigg\} \\
& + \frac{2}{3n^2} \left( \frac{\partial u_k}{\partial x_k} \right) \left\{ nR^{(2,0)}(x, \hat{x}) - \left[ nS_{i,l}^{(1,0,1)}(x, \hat{x}, x) \right. \right. \\
& \quad - R^{(0,0)}(x, \hat{x}) R_{i,l}^{(1,1)}(x, x) - 2R_i^{(1,0)}(x, \hat{x}) R_l^{(1,0)}(x, x) \\
& \quad - \frac{n}{9B_1} \left( \frac{\partial u_l}{\partial x_l} \right) \left( R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right) \\
& \quad \left. \left. - \frac{n^2KT}{3B_1m} \frac{\partial}{\partial x_l} \left( \frac{1}{n} R^{(1,0)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{\partial}{\partial x_i} \left\{ - \frac{4}{3n^2} R_k^{(1,0)}(x, \hat{x}) R_{k,i}^{(1,1)}(x, x) - \frac{2}{3n^2} R_i^{(1,0)}(x, \hat{x}) R_{k,k}^{(1,1)}(x, x) \right. \\
& \quad + \frac{5}{3n^2} R_i^{(1,0)}(x, \hat{x}) \left[ \frac{3KT}{m} R^{(0,0)}(x, x) - R^{(0,2)}(x, x) \right] \\
& \quad + \frac{5}{3n^2} R_i^{(1,0)}(x, x) \left[ \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) - R^{(2,0)}(x, \hat{x}) \right] \\
& \quad + \frac{5}{3n^2} R^{(0,0)}(x, \hat{x}) \left[ \frac{3KT}{m} R_i^{(1,0)}(x, x) - R_i^{(1,2)}(x, x) \right] \\
& \quad + \frac{5}{3n} \left[ S_i^{(1,0,2)}(x, \hat{x}, x) - \frac{3KT}{m} S_i^{(1,0,0)}(x, \hat{x}, x) \right] \\
& \quad + \frac{2KT}{9B_1mn} R_i^{(1,0)}(x, \hat{x}) \left( \frac{\partial u_k}{\partial x_k} \right) - \frac{KT}{3B_1mn} R_k^{(1,0)}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\
& \quad - \frac{5K}{6B_1mn} \left( R^{(2,0)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,0)}(x, \hat{x}) \right) \frac{\partial T}{\partial x_i} \\
& \quad - \frac{5KT^2}{12B_1m} \frac{\partial}{\partial x_i} \left[ \frac{1}{nT} R^{(2,0)}(x, \hat{x}) - \frac{3K}{mn} R^{(0,0)}(x, \hat{x}) \right] \\
& \quad \left. + \frac{5KT}{m} R_i^{(1,0)}(x, \hat{x}) \right\} + \frac{\partial R_k^{(2,1)}}{\partial \hat{x}_k} = 0 \tag{127}
\end{aligned}$$

$$\begin{aligned}
& \frac{\mathcal{D} R^{(2,1)}_j}{\mathcal{D} t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) R^{(2,1)}_j + 2 \frac{Du_i}{Dt} R^{(1,1)}_{ij} + \frac{\hat{D}\hat{u}_j}{\hat{D}t} R^{(2,0)} \\
& + \frac{2}{n^2} \frac{\partial u_i}{\partial \hat{x}_k} \left\{ nS^{(1,1,1)}_{ij,k}(x, \hat{x}, x) - R^{(1,1)}_{ik}(x, x) R^{(0,1)}_j(x, \hat{x}) \right. \\
& \quad - R^{(1,1)}_{ij}(x, \hat{x}) R^{(1,0)}_k(x, x) - R^{(1,1)}_{kj}(x, \hat{x}) R^{(1,0)}_i(x, x) \\
& \quad - \frac{n}{18B_1} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \left[ R^{(2,1)}_j(x, \hat{x}) - \frac{3KT}{m} R^{(0,1)}_j(x, \hat{x}) \right] \\
& \quad \left. - \frac{n^2KT}{6B_1m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R^{(1,1)}_{ij}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R^{(1,1)}_{kj}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{2}{3n^2} \left( \frac{\partial u_k}{\partial x_k} \right) \left\{ n^2 R^{(2,1)}_j(x, \hat{x}) - \left[ nS^{(1,1,1)}_{l,j,i}(x, \hat{x}, x) \right. \right. \\
& \quad - R^{(0,1)}_j(x, \hat{x}) R^{(1,1)}_{li}(x, x) - 2R^{(1,1)}_{lj}(x, \hat{x}) R^{(1,0)}_i(x, x) \\
& \quad - \frac{n}{9B_1} \left( \frac{\partial u_l}{\partial x_i} \right) \left( R^{(2,1)}_j(x, \hat{x}) - \frac{3KT}{m} R^{(0,1)}_j(x, \hat{x}) \right) \\
& \quad \left. \left. - \frac{n^2KT}{3B_1m} \frac{\partial}{\partial x_l} \left( \frac{1}{n} R^{(1,1)}_{lj}(x, \hat{x}) \right) \right] \right\} \\
& + R^{(2,1)}_k \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial}{\partial x_i} \left\{ - \frac{4}{3n^2} R^{(1,1)}_{kj}(x, \hat{x}) R^{(1,1)}_{ki}(x, x) \right. \\
& \quad - \frac{2}{3n^2} R^{(1,1)}_{ij}(x, \hat{x}) R^{(1,1)}_{kk}(x, x) + \frac{5}{3n^2} R^{(1,1)}_{ij}(x, \hat{x}) \\
& \quad \times \left[ \frac{3KT}{m} R^{(0,0)}(x, x) - R^{(0,2)}(x, x) \right] \\
& \quad + \frac{5}{3n^2} R^{(1,0)}_i(x, x) \left[ \frac{3KT}{m} R^{(0,1)}_j(x, \hat{x}) - R^{(2,1)}_j(x, \hat{x}) \right] \\
& \quad + \frac{5}{3n^2} R^{(0,1)}_j(x, \hat{x}) \left[ \frac{3KT}{m} R^{(1,0)}_i(x, x) - R^{(1,2)}_i(x, x) \right] \\
& \quad \left. + \frac{5}{3n} \left[ S^{(1,1,2)}_{ij}(x, \hat{x}, x) - \frac{3KT}{m} S^{(1,1,0)}_{ij}(x, \hat{x}, x) \right] =
\end{aligned}$$

$$\begin{aligned}
 & + \frac{2KT}{9B_1mn} R^{(1,1)}_{ij}(x, \hat{x}) \left( \frac{\partial u_k}{\partial x_k} \right) - \frac{KT}{3B_1mn} R^{(1,1)}_{kj}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\
 & - \frac{5K}{6B_1mn} \left( R^{(2,1)}_j(x, \hat{x}) - \frac{3KT}{m} R^{(0,1)}_j(x, \hat{x}) \right) \frac{\partial T}{\partial x_i} \\
 & - \frac{5KT^2}{12B_1m} \frac{\partial}{\partial x_i} \left[ \frac{1}{nT} R^{(2,1)}_j(x, \hat{x}) - \frac{3K}{mn} R^{(0,1)}_j(x, \hat{x}) \right] \\
 & + \frac{5KT}{m} R^{(1,1)}_{ij}(x, \hat{x}) \left. \right\} \\
 & + \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} S^{(2,1,1)}_{j,k}(x, \hat{x}, \hat{x}) - \frac{1}{\hat{n}^2} R^{(1,1)}_{j,k}(\hat{x}, \hat{x}) R^{(2,0)}(x, \hat{x}) \right. \\
 & - \frac{1}{\hat{n}^2} R^{(2,1)}_j(x, \hat{x}) R^{(1,0)}_k(\hat{x}, \hat{x}) - \frac{1}{\hat{n}^2} R^{(2,1)}_k(x, \hat{x}) R^{(1,0)}_j(\hat{x}, \hat{x}) \\
 & - \frac{1}{18B_1\hat{n}} \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) \left[ R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right] \\
 & - \frac{KT}{6B_1m} \left[ \frac{\partial}{\partial \hat{x}_k} \left( \frac{1}{\hat{n}} R^{(2,1)}_j(x, \hat{x}) \right) + \frac{\partial}{\partial \hat{x}_j} \left( \frac{1}{\hat{n}} R^{(2,1)}_k(x, \hat{x}) \right) \right] \left. \right\} \\
 & + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left\{ R^{(2,2)}(x, \hat{x}) - \left[ \frac{1}{\hat{n}} S^{(2,1,1)}_{l,l}(x, \hat{x}, \hat{x}) \right. \right. \\
 & - \frac{1}{\hat{n}^2} R^{(2,0)}(x, \hat{x}) R^{(1,1)}_{l,l}(\hat{x}, \hat{x}) - \frac{2}{\hat{n}^2} R^{(2,1)}_l(x, \hat{x}) R^{(1,0)}_l(\hat{x}, \hat{x}) \\
 & - \frac{1}{9B_1\hat{n}} \left( \frac{\partial \hat{u}_l}{\partial \hat{x}_j} \right) \left( R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right) \\
 & \left. \left. - \frac{n^2K\hat{T}}{3B_1m} \frac{\partial}{\partial \hat{x}_l} \left( \frac{1}{\hat{n}} R^{(2,1)}_l(x, \hat{x}) \right) \right] \right\} = 0 \quad (1 \leq j \leq 3) \quad (128)
 \end{aligned}$$

$$\begin{aligned}
 & \frac{\mathcal{D} R^{(2,2)}}{\mathcal{D} t} + \left( \frac{\partial u_k}{\partial x_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) R^{(2,2)} + 2 \frac{Du_i}{Dt} R^{(1,2)}_i + 2 \frac{\hat{D}\hat{u}_j}{\hat{D}t} R^{(2,1)}_j \\
 & + \frac{2}{n^2} \frac{\partial u_i}{\partial x_k} \left\{ nS^{(1,2,1)}_{i,k}(x, \hat{x}, x) - R^{(1,1)}_{i,k}(x, x) R^{(0,2)}(x, \hat{x}) \right. \\
 & \left. - R^{(1,2)}_i(x, \hat{x}) R^{(1,0)}_k(x, x) - R^{(1,2)}_k(x, \hat{x}) R^{(1,0)}_i(x, x) = \right.
 \end{aligned}$$

$$\begin{aligned}
& - \frac{n}{18B_1} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \left[ R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right] \\
& - \frac{n^2KT}{6B_1m} \left[ \frac{\partial}{\partial x_k} \left( \frac{1}{n} R^{(1,2)}(x, \hat{x}) \right) + \frac{\partial}{\partial x_i} \left( \frac{1}{n} R^{(1,2)}(x, \hat{x}) \right) \right] \Bigg\} \\
& + \frac{2}{3n^2} \left( \frac{\partial u_k}{\partial x_k} \right) \left\{ n^2 R^{(2,2)}(x, \hat{x}) - \left[ nS^{(1,2,1)}(x, \hat{x}, x) - R^{(0,2)}(x, \hat{x}) R^{(1,1)}(x, x) \right. \right. \\
& \quad - 2R^{(1,2)}(x, \hat{x}) R^{(1,0)}(x, x) \\
& \quad - \frac{n}{9B_1} \left( \frac{\partial u_i}{\partial x_i} \right) \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \\
& \quad \left. \left. - \frac{n^2KT}{3B_1m} \frac{\partial}{\partial x_i} \left( \frac{1}{n} R^{(1,2)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{2}{\hat{n}^2} \frac{\partial \hat{u}_j}{\partial \hat{x}_k} \left\{ \hat{n}S^{(2,1,1)}(x, \hat{x}, \hat{x}) - R^{(1,1)}(\hat{x}, \hat{x}) R^{(2,0)}(x, \hat{x}) \right. \\
& \quad - R^{(2,1)}(x, \hat{x}) R^{(1,0)}(\hat{x}, \hat{x}) - R^{(2,1)}(x, \hat{x}) R^{(1,0)}(\hat{x}, \hat{x}) \\
& \quad - \frac{\hat{n}}{18B_1} \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) \left[ R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right] \\
& \quad \left. - \frac{\hat{n}^2K\hat{T}}{6B_1m} \left[ \frac{\partial}{\partial \hat{x}_k} \left( \frac{1}{\hat{n}} R^{(2,1)}(x, \hat{x}) \right) + \frac{\partial}{\partial \hat{x}_j} \left( \frac{1}{\hat{n}} R^{(2,1)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{2}{3\hat{n}^2} \left( \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) \left\{ \hat{n}^2 R^{(2,2)}(x, \hat{x}) - \left[ \hat{n}S^{(2,1,1)}(x, \hat{x}, \hat{x}) - R^{(2,0)}(x, \hat{x}) R^{(1,1)}(\hat{x}, \hat{x}) \right. \right. \\
& \quad - 2R^{(2,1)}(x, \hat{x}) R^{(1,0)}(\hat{x}, \hat{x}) - \frac{\hat{n}}{9B_1} \left( \frac{\partial \hat{u}_i}{\partial \hat{x}_i} \right) \left( R^{(2,2)}(x, \hat{x}) \right. \\
& \quad \left. \left. - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) - \frac{\hat{n}^2K\hat{T}}{3B_1m} \frac{\partial}{\partial \hat{x}_i} \left( \frac{1}{\hat{n}} R^{(2,1)}(x, \hat{x}) \right) \right] \right\} \\
& + \frac{\partial}{\partial x_i} \left\{ - \frac{4}{3n^2} R^{(1,2)}(x, \hat{x}) R^{(1,1)}(x, x) - \frac{2}{3n^2} R^{(1,2)}(x, \hat{x}) R^{(1,1)}(x, x) = \right.
\end{aligned}$$

$$\begin{aligned}
& + \frac{5}{3n^2} R_i^{(1,2)}(x, \hat{x}) \left[ \frac{3KT}{m} R^{(0,0)}(x, x) - R^{(0,2)}(x, x) \right] \\
& + \frac{5}{3n^2} R_i^{(1,0)}(x, x) \left[ \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) - R^{(2,2)}(x, \hat{x}) \right] \\
& + \frac{5}{3n^2} R^{(0,2)}(x, \hat{x}) \left[ \frac{3KT}{m} R_i^{(1,0)}(x, x) - R_i^{(1,2)}(x, x) \right] \\
& + \frac{5}{3n} \left[ S_i^{(1,2,2)}(x, \hat{x}, x) - \frac{3KT}{m} S_i^{(1,2,0)}(x, \hat{x}, x) \right] \\
& + \frac{2KT}{9B_1mn} R_i^{(1,2)}(x, \hat{x}) \left( \frac{\partial u_k}{\partial x_k} \right) - \frac{KT}{3B_1mn} R_k^{(1,2)}(x, \hat{x}) \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \\
& - \frac{5K}{6B_1mn} \left( R^{(2,2)}(x, \hat{x}) - \frac{3KT}{m} R^{(0,2)}(x, \hat{x}) \right) \frac{\partial T}{\partial x_i} \\
& - \frac{5KT^2}{12B_1m} \frac{\partial}{\partial x_i} \left[ \frac{1}{nT} R^{(2,2)}(x, \hat{x}) - \frac{3K}{mn} R^{(0,2)}(x, \hat{x}) \right] + \frac{5KT}{m} R_i^{(1,2)}(x, \hat{x}) \left. \right\} \\
& + \frac{\partial}{\partial \hat{x}_i} \left\{ - \frac{4}{3\hat{n}^2} R_k^{(2,1)}(x, \hat{x}) R_{i,k}^{(1,1)}(x, \hat{x}) - \frac{2}{3\hat{n}^2} R_i^{(2,1)}(x, \hat{x}) R_{k,k}^{(1,1)}(\hat{x}, \hat{x}) \right. \\
& \quad + \frac{5}{3\hat{n}^2} R_i^{(2,1)}(x, \hat{x}) \left[ \frac{3K\hat{T}}{m} R^{(0,0)}(\hat{x}, \hat{x}) - R^{(2,0)}(\hat{x}, \hat{x}) \right] \\
& \quad + \frac{5}{3\hat{n}^2} R_i^{(0,1)}(\hat{x}, \hat{x}) \left[ \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) - R^{(2,2)}(x, \hat{x}) \right] \\
& \quad + \frac{5}{3\hat{n}^2} R^{(2,0)}(x, \hat{x}) \left[ \frac{3K\hat{T}}{m} R_i^{(0,1)}(\hat{x}, \hat{x}) - R_i^{(2,1)}(\hat{x}, \hat{x}) \right] \\
& \quad + \frac{5}{3\hat{n}} \left[ S_i^{(2,1,2)}(x, \hat{x}, \hat{x}) - \frac{3K\hat{T}}{m} S_i^{(2,0,1)}(x, \hat{x}, \hat{x}) \right] \\
& \quad + \frac{2K\hat{T}}{9B_1m\hat{n}} R_i^{(2,1)}(x, \hat{x}) \left( \frac{\partial \hat{u}_k}{\partial \hat{x}_k} \right) - \frac{K\hat{T}}{3B_1m\hat{n}} R_k^{(2,1)}(x, \hat{x}) \left( \frac{\partial \hat{u}_i}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_i} \right) \\
& \quad - \frac{5K}{6B_1m\hat{n}} \left( R^{(2,2)}(x, \hat{x}) - \frac{3K\hat{T}}{m} R^{(2,0)}(x, \hat{x}) \right) \frac{\partial \hat{T}}{\partial \hat{x}_i} \\
& \quad - \frac{5K\hat{T}^2}{12B_1m} \frac{\partial}{\partial \hat{x}_i} \left[ \frac{1}{\hat{n}\hat{T}} R^{(2,2)}(x, \hat{x}) - \frac{3K}{m\hat{n}} R^{(2,0)}(x, \hat{x}) \right] \\
& \quad \left. + \frac{5K\hat{T}}{m} R_i^{(2,1)}(x, \hat{x}) \right\} = 0 \tag{129}
\end{aligned}$$

Equations (53)–(55), together with (114)–(129), represent 155 equations which form the system of approximate equations of order  $1\frac{2}{3}$  governing the motion of turbulent flows. The system of the equations will be greatly simplified if the flow is supposed to be incompressible:

$$\begin{aligned} \frac{\partial S_{ij,k}^{(1,1,1)}}{\partial \hat{x}_k} &= 0 \quad (1 \leq i, j \leq 3) \\ \frac{\partial S_{j,k}^{(2,1,1)}}{\partial \hat{x}_k} &= 0 \quad (1 \leq j \leq 3) \\ \frac{\Delta S_{ij,k}^{(1,1,1)}}{\Delta t} + \frac{\partial u_i}{\partial x_k} S_{k,j,l}^{(1,1,1)} + \frac{\partial \hat{u}_j}{\partial \hat{x}_k} S_{i,k,l}^{(1,1,1)} + \frac{\partial \hat{u}_l}{\partial \hat{x}_k} S_{ij,k}^{(1,1,1)} \\ &+ \frac{\partial}{\partial x_k} \left\{ \frac{1}{n} [R_{ij}^{(1,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(x, \hat{x}) + R_{kj}^{(1,1)}(x, \hat{x}) R_{i,l}^{(1,1)}(x, \hat{x})] \right\} \\ &+ \frac{1}{3} \frac{\partial}{\partial x_i} \left[ S_{j,l}^{(2,1,1)} - \frac{2}{n} R_{kj}^{(1,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(x, \hat{x}) \right] \\ &+ \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} [R_{i,k}^{(1,1)}(x, \hat{x}) R_{j,l}^{(1,1)}(\hat{x}, \hat{x}) + R_{ij}^{(1,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(\hat{x}, \hat{x})] \right\} \\ &+ \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} \left[ S_{i,l}^{(1,2,1)} - \frac{2}{\hat{n}} R_{i,k}^{(1,1)}(x, \hat{x}) R_{k,l}^{(1,1)}(\hat{x}, \hat{x}) \right] \\ &+ \frac{\partial}{\partial \hat{x}_k} \left\{ \frac{1}{\hat{n}} [R_{i,k}^{(1,1)}(x, \hat{x}) R_{j,l}^{(1,1)}(\hat{x}, \hat{x}) + R_{i,l}^{(1,1)}(x, \hat{x}) R_{j,k}^{(1,1)}(\hat{x}, \hat{x})] \right\} \\ &+ \frac{1}{3} \frac{\partial}{\partial \hat{x}_l} \left[ S_{ij}^{(1,1,2)} - \frac{2}{\hat{n}} R_{i,k}^{(1,1)}(x, \hat{x}) R_{j,k}^{(1,1)}(\hat{x}, \hat{x}) \right] = 0 \quad (1 \leq i, j, l \leq 3) \\ \frac{\partial R_{i,k}^{(1,1)}}{\partial \hat{x}_k} &= 0 \quad (1 \leq i \leq 3) \\ \frac{\partial R_k^{(2,1)}}{\partial \hat{x}_k} &= 0 \\ \textcircled{D} \frac{R_{ij}^{(1,1)}}{\textcircled{D} t} + R_{k,j}^{(1,1)} \frac{\partial u_i}{\partial x_k} + R_{i,k}^{(1,1)} \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{1}{n} \frac{\partial}{\partial x_k} [S_{ij,k}^{(1,1,1)}(x, \hat{x}, x)] \\ &- \kappa \frac{\partial}{\partial x_k} \left[ \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) R_j^{(2,1)}(x, \hat{x}) \right] - \nu \Delta R_{ij}^{(1,1)}(x, \hat{x}) \\ &+ \frac{1}{3} \frac{\partial}{\partial x_i} R_j^{(2,1)}(x, \hat{x}) - \frac{1}{3n} \frac{\partial}{\partial x_i} [S_{ij,l}^{(1,1,1)}(x, \hat{x}, x)] \\ &+ \frac{1}{n} \frac{\partial}{\partial \hat{x}_k} [S_{ij,k}^{(1,1,1)}(x, \hat{x}, \hat{x})] = \end{aligned}$$



$$\begin{aligned}
& -\kappa \frac{\partial}{\partial \hat{x}_k} \left[ \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) R^{(1,2)}(x, \hat{x}) \right] \\
& -\nu \hat{\Delta} R^{(1,1)}(x, \hat{x}) + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} R^{(1,2)}(x, \hat{x}) \\
& - \frac{1}{3n} \frac{\partial}{\partial \hat{x}_j} [S^{(1,1,1)}(x, \hat{x}, \hat{x})] = 0 \\
& (1 \leq i, j \leq 3)
\end{aligned}$$

where  $\nu = \mu/\rho$  and  $\kappa = 1/18nB_1$ . The constant  $\kappa$  is a new transport coefficient. The existence of the transport coefficient  $\kappa$  means that the deformation of the fluid produces not only the stress, but also the stress correlation. This fact is a consequence of the Enskog-Chapman expansion.

## 15. A SUFFICIENT CONDITION FOR A FLOW BEING LAMINAR

If we neglect the three-point correlations  $S$ 's, the last equation in the last section will take the following form:

$$\begin{aligned}
& \frac{\partial R^{(1,1)}_{ij}}{\partial t} + u_k \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} + \hat{u}_k \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} + R^{(1,1)}_{kj} \frac{\partial u_i}{\partial x_k} + R^{(1,1)}_{ik} \frac{\partial \hat{u}_j}{\partial \hat{x}_k} \\
& -\kappa \frac{\partial}{\partial x_k} \left[ \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) R^{(2,1)}(x, \hat{x}) \right] \\
& -\nu \Delta R^{(1,1)}(x, \hat{x}) + \frac{1}{3} \frac{\partial}{\partial x_i} R^{(2,1)}(x, \hat{x}) \\
& -\kappa \frac{\partial}{\partial \hat{x}_k} \left[ \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) R^{(1,2)}(x, \hat{x}) \right] - \nu \hat{\Delta} R^{(1,1)}(x, \hat{x}) \\
& + \frac{1}{3} \frac{\partial}{\partial \hat{x}_j} R^{(1,2)}(x, \hat{x}) = 0 \quad (1 \leq i, j \leq 3) \tag{130}
\end{aligned}$$

In the classical theory, a flow is a solution of the Navier-Stokes equations, and a laminar flow is a stable flow. In our scheme, a flow is a solution of the system of partial differential equations which govern not only the evolution of the density and the velocity of the flow, but also that of the correlations, and a laminar flow is a flow with vanishing correlations  $R^{(1,1)}_{ij}$ . Now we are going to get a sufficient condition for a flow being laminar in our scheme.

From (130) we have

$$\begin{aligned} & \frac{\partial u_k}{\partial x_i} \frac{\partial R_{ij}^{(1,1)}}{\partial x_k} + \frac{\partial R_{kj}^{(1,1)}}{\partial x_i} \frac{\partial u_i}{\partial x_k} - \kappa \frac{\partial^2}{\partial x_i \partial x_k} \left[ \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) R_j^{(2,1)} \right] \\ & + \frac{1}{3} \Delta R_j^{(2,1)} = 0 \\ & - \frac{\partial}{\partial x_i} \left\{ \left[ \frac{1}{3} \delta_{ik} - \kappa \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \right] \frac{\partial R_j^{(2,1)}}{\partial x_k} \right\} + \kappa \frac{\partial}{\partial x_i} (\Delta u_i R_j^{(2,1)}) \\ & = 2 \frac{\partial u_i}{\partial x_k} \frac{\partial R_{kj}^{(1,1)}}{\partial x_i} \end{aligned}$$

Now we make the following assumption: All the correlations take the null boundary value. Having made this assumption, we have

$$\begin{aligned} & \int \left[ \frac{1}{3} \delta_{ik} - \kappa \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) \right] \frac{\partial R_j^{(2,1)}}{\partial x_i} \frac{R_j^{(2,1)}}{\partial x_k} dx d\hat{x} \\ & = 2 \int R_j^{(2,1)} \frac{\partial u_i}{\partial x_k} \frac{\partial R_{kj}^{(1,1)}}{\partial x_i} dx d\hat{x} \end{aligned}$$

In deriving the above equality we have taken the following fact, which is easy to verify, into consideration:

$$\int R_j^{(2,1)} \frac{\partial}{\partial x_i} [\Delta u_i R_j^{(2,1)}] dx d\hat{x} = 0$$

Let  $\alpha \geq \beta \geq \gamma$  be the eigenvalues of the stretching tensor  $(\partial u_i / \partial x_k + \partial u_k / \partial x_i)$ . Assuming that

$$\frac{1}{3} > \kappa \alpha \quad (131)$$

we have

$$\begin{aligned} & \int \left[ \frac{\partial R_j^{(2,1)}}{\partial x_i} \right]^2 dx d\hat{x} \leq \frac{2}{\frac{1}{3} - \kappa \alpha} \left| \int \frac{\partial R_j^{(2,1)}}{\partial x_k} \frac{\partial u_i}{\partial x_k} R_{kj}^{(1,1)} dx d\hat{x} \right| \\ & \leq \frac{6M}{1 - 3\kappa \alpha} \left[ \int \left( \frac{\partial R_j^{(2,1)}}{\partial x_i} \right)^2 dx d\hat{x} \right]^{1/2} \left[ \int (R_{ij}^{(1,1)})^2 dx d\hat{x} \right]^{1/2} \end{aligned}$$

where  $M$  is the norm of the matrix  $(\partial u_i / \partial x_k)$  in the three-dimensional

Euclidean space. Hence,

$$\left[ \int \left( \frac{\partial R^{(2,1)}_{ij}}{\partial x_i} \right)^2 dx d\hat{x} \right]^{1/2} \leq \frac{6M}{1-3\kappa\alpha} \left[ \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \right]^{1/2} \quad (132)$$

On the other hand, we get the following equality from equality (130):

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int (R^{(1,1)}_{ij})^2 dx d\hat{x} + \frac{1}{2} \int R^{(1,1)}_{ij} R^{(1,1)}_{kj} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) dx d\hat{x} \\ & + \frac{1}{2} \int R^{(1,1)}_{i,k} R^{(1,1)}_{ij} \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) dx d\hat{x} \\ & + \kappa \int \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \left( \frac{\partial u_i}{\partial x_k} + \frac{\partial u_k}{\partial x_i} \right) R^{(2,1)}_j dx d\hat{x} \\ & + \kappa \int \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \left( \frac{\partial \hat{u}_j}{\partial \hat{x}_k} + \frac{\partial \hat{u}_k}{\partial \hat{x}_j} \right) R^{(1,2)}_i dx d\hat{x} \\ & + \nu \int \left[ \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 + \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} = 0 \end{aligned} \quad (133)$$

In virtue of the well-known inequality<sup>(3)</sup>

$$A \left\{ \int \left[ \left( \frac{\partial f}{\partial x_k} \right)^2 + \left( \frac{\partial f}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} \right\}^{1/2} \geq \left( \int |f|^2 dx d\hat{x} \right)^{1/2} \quad (134)$$

We deduce the following inequality from (133):

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \leq -\nu \int \left[ \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 + \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} \\ & + \max(\alpha, -\gamma) \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \\ & + \kappa(\alpha^2 + \beta^2 + \gamma^2)^{1/2} \left\{ \left[ \int \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 dx d\hat{x} \right]^{1/2} \left[ \int (R^{(2,1)}_j)^2 dx d\hat{x} \right]^{1/2} \right. \\ & \left. + \left[ \int \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 dx d\hat{x} \right]^{1/2} \left[ \int (R^{(1,2)}_i)^2 dx d\hat{x} \right]^{1/2} \right\} \end{aligned}$$

$$\begin{aligned}
& + \left[ \int \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 dx d\hat{x} \right]^{1/2} \left[ \int (R^{(1,2)}_i)^2 dx d\hat{x} \right]^{1/2} \Big\} \\
\leq & -\nu \int \left[ \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 + \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} \\
& + \max(\alpha, -\gamma) \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \\
& + \kappa(\alpha^2 + \beta^2 + \gamma^2)^{1/2} \left\{ \int \left[ \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 + \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} \right\}^{1/2} \\
& \times \frac{24AM}{1-3\kappa\alpha} \left[ \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \right]^{1/2} \\
\leq & -\nu \int \left[ \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 + \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} \\
& + \max(\alpha, -\gamma) \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \\
& + \frac{24\kappa AM(\alpha^2 + \beta^2 + \gamma^2)^{1/2}}{1-3\kappa\alpha} \\
& \cdot \frac{1}{2} \left\{ A^{1/2} \int \left[ \left( \frac{\partial R^{(1,1)}_{ij}}{\partial x_k} \right)^2 + \left( \frac{\partial R^{(1,1)}_{ij}}{\partial \hat{x}_k} \right)^2 \right] dx d\hat{x} \right. \\
& \quad \left. + \frac{1}{A^{1/2}} \int (R^{(1,1)}_{ij})^2 dx d\hat{x} \right\} \\
\leq & \left[ -\frac{\nu}{A} + \frac{24\kappa A^{1/2} M(\alpha^2 + \beta^2 + \gamma^2)^{1/2}}{1-3\kappa\alpha} + \max(\alpha, -\gamma) \right] \\
& \times \int (R^{(1,1)}_{ij})^2 dx d\hat{x}
\end{aligned}$$

if

$$\nu \geq \frac{24\kappa(A)^{3/2}M(\alpha^2 + \beta^2 + \gamma^2)^{1/2}}{1 - 3\kappa\alpha}$$

Now it is easy to see that a sufficient condition for the flow being laminar flow is the inequality

$$\nu \geq \frac{24\kappa A^{3/2}M(\alpha^2 + \beta^2 + \gamma^2)^{1/2}}{1 - 3\kappa\alpha} + A \max(\alpha, -\gamma)$$

combined with inequality (131). It is worth while mentioning that if  $\kappa$  were equal to zero, the conclusions in our theory and in the classical stability theory<sup>(3)</sup> would be identical. This fact is very interesting, because the starting points of the two theories are quite different. We think the new transport coefficient  $\kappa$  will play an important role in the further study of turbulence phenomena.

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